



→ EARTH OBSERVATION AND CRYOSPHERE SCIENCE

Advancing Knowledge of Cryosphere-Atmosphere-Ocean Interactions from Space

A Comparison of Sea-Ice Freeboard and Thickness Distributions from Aircraft Data and CryoSat-2

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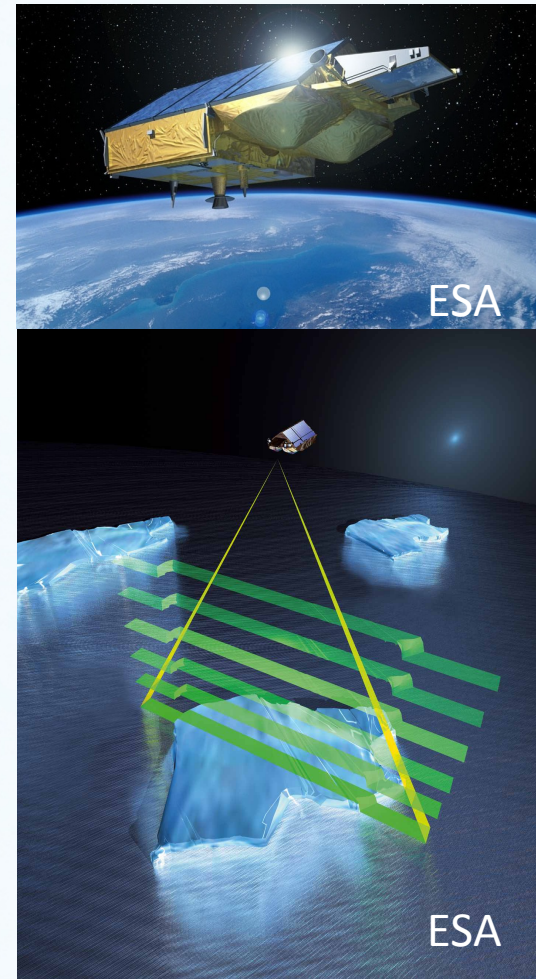
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Introduction

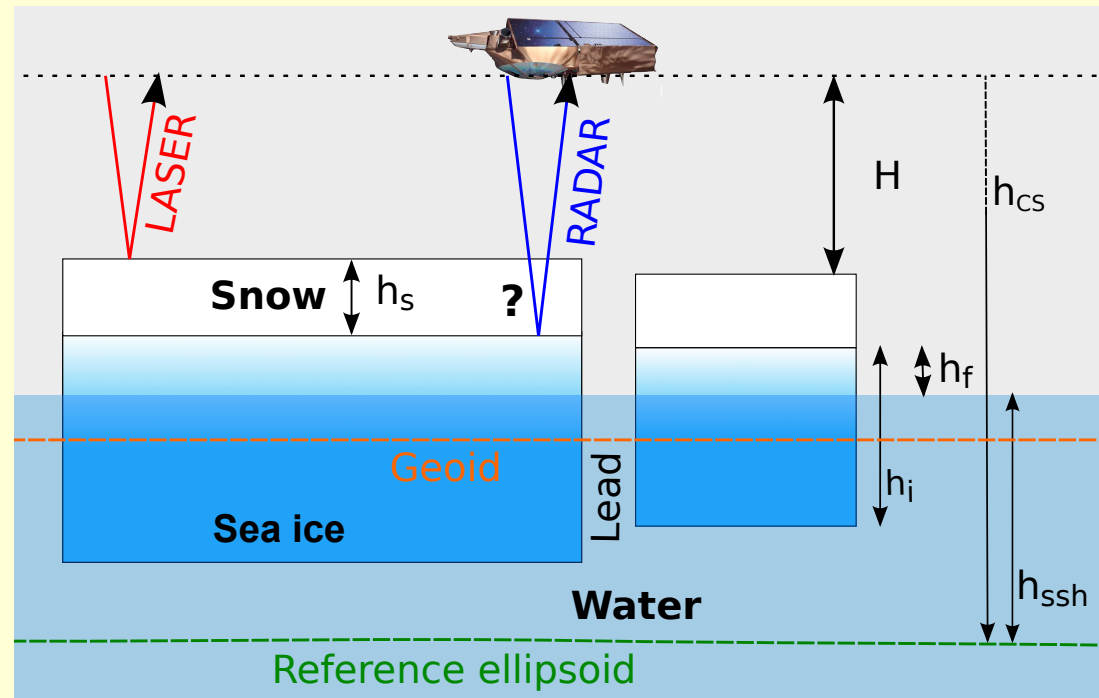
- CryoSat-2 measures the distance between satellite and surface.
- It is crucial to measure the reflecting horizon very accurately.



Measuring sea-ice freeboard

- h_i Sea-ice thickness
- h_s Snow depth
- h_{fs} Snow freeboard
- h_{fi} Ice freeboard
- h_{ssh} Sea-surface height
- h_{GPS} CryoSat-2/aircraft altitude
- H Measured distance

$$h_{fs} = h_{GPS} - H - h_{ssh}$$



Introduction

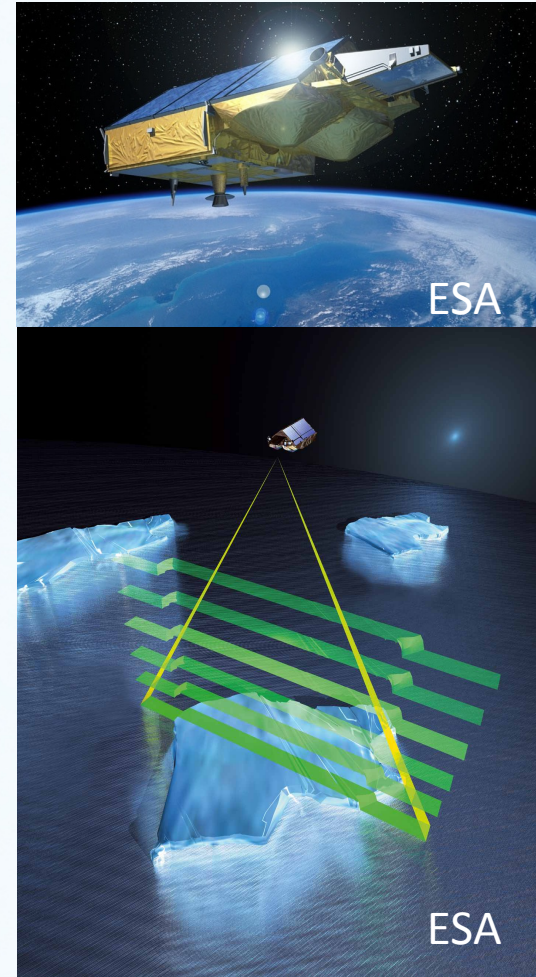
- CryoSat-2 measures the distance between satellite and surface
- It is crucial to measure the reflecting horizon very accurate

Hypothesis:

It is assumed that the CryoSat-2 radar is penetrating a cold and dry snow layer.

Objective of this study:

Testing the hypothesis with a comparison between airborne laser, radar and electromagnetic sounding and CryoSat-2 measurements over multi year ice in the Lincoln Sea.

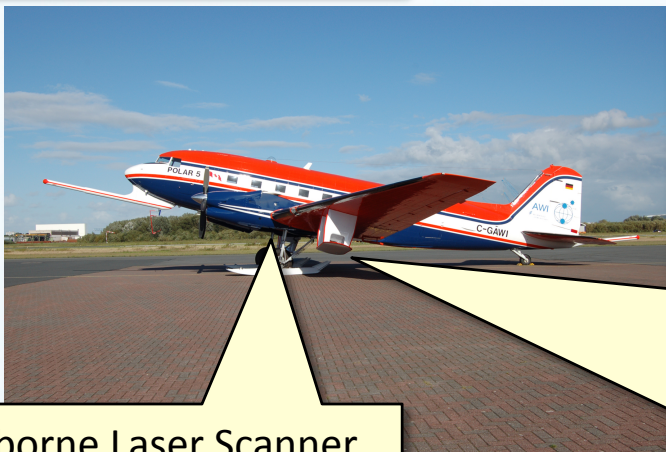


CryoSat Validation Experiment (CryoVEx)



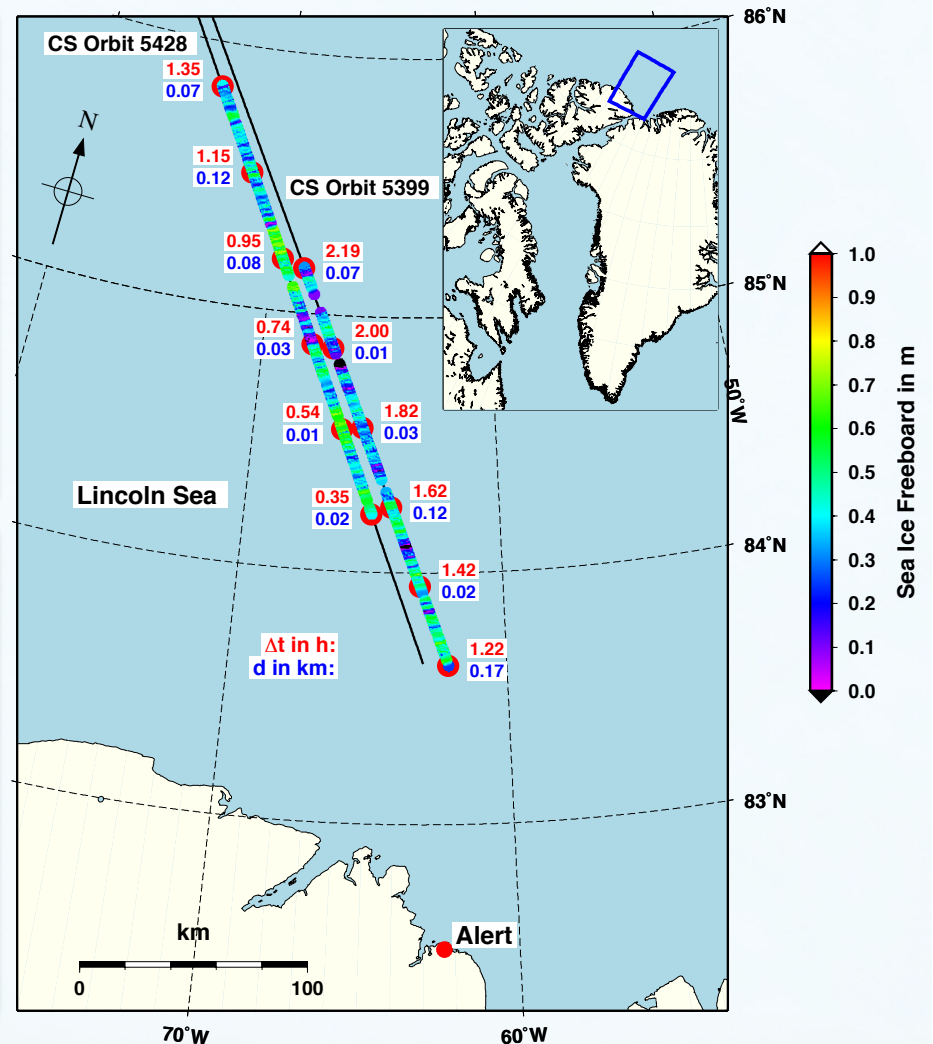
Airborne Laser Scanner

Airborne
Radar
Altimeter:
ASIRAS

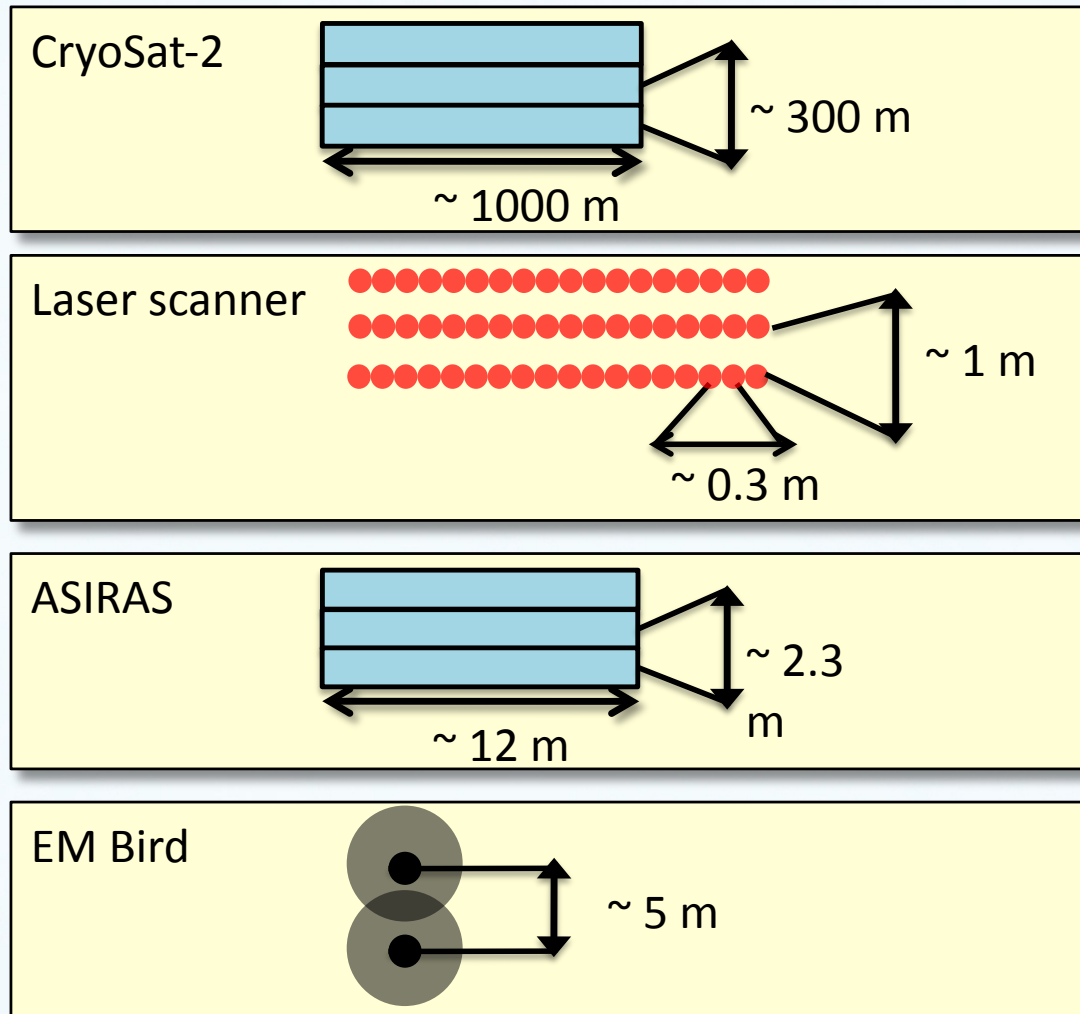


Airborne Laser Scanner

EM Induction
Sounding:
EM BIRD

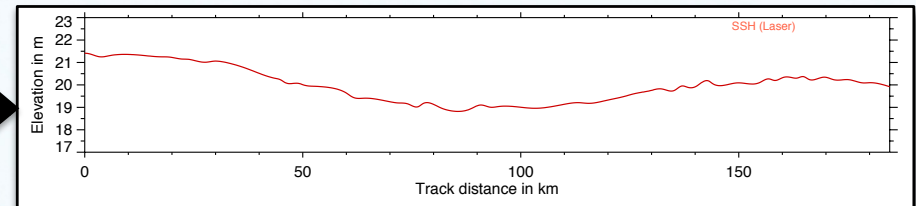


Data resolution - overview



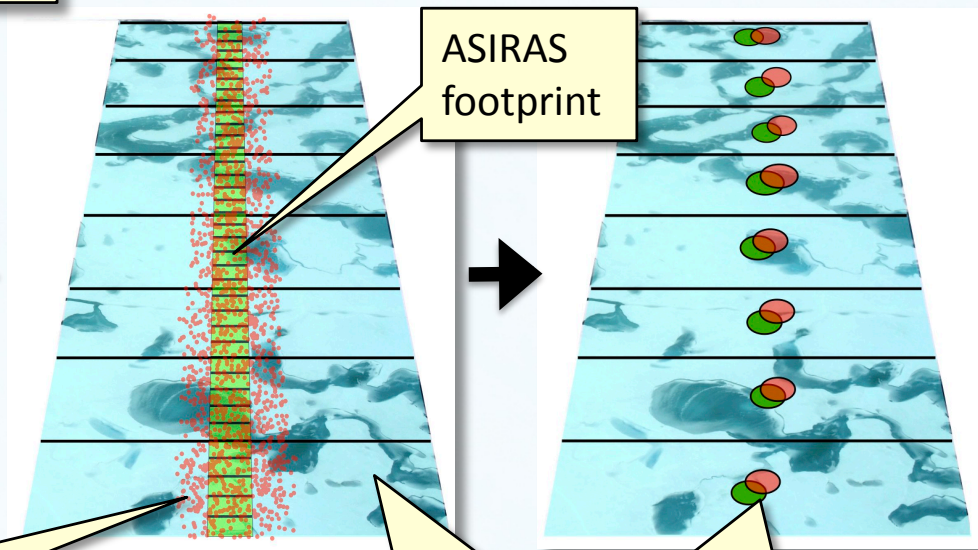
Data and methods

1. A manually picked sea-surface height from laser scanner data is used to calculate the CryoSat-2 and ASIRAS freeboard.



2. Laser scanner: A weighted average is formed of across-track data points.

3. Laser, ASIRAS, EM: Assigning to the respective CryoSat footprint and averaging the enclosed points.



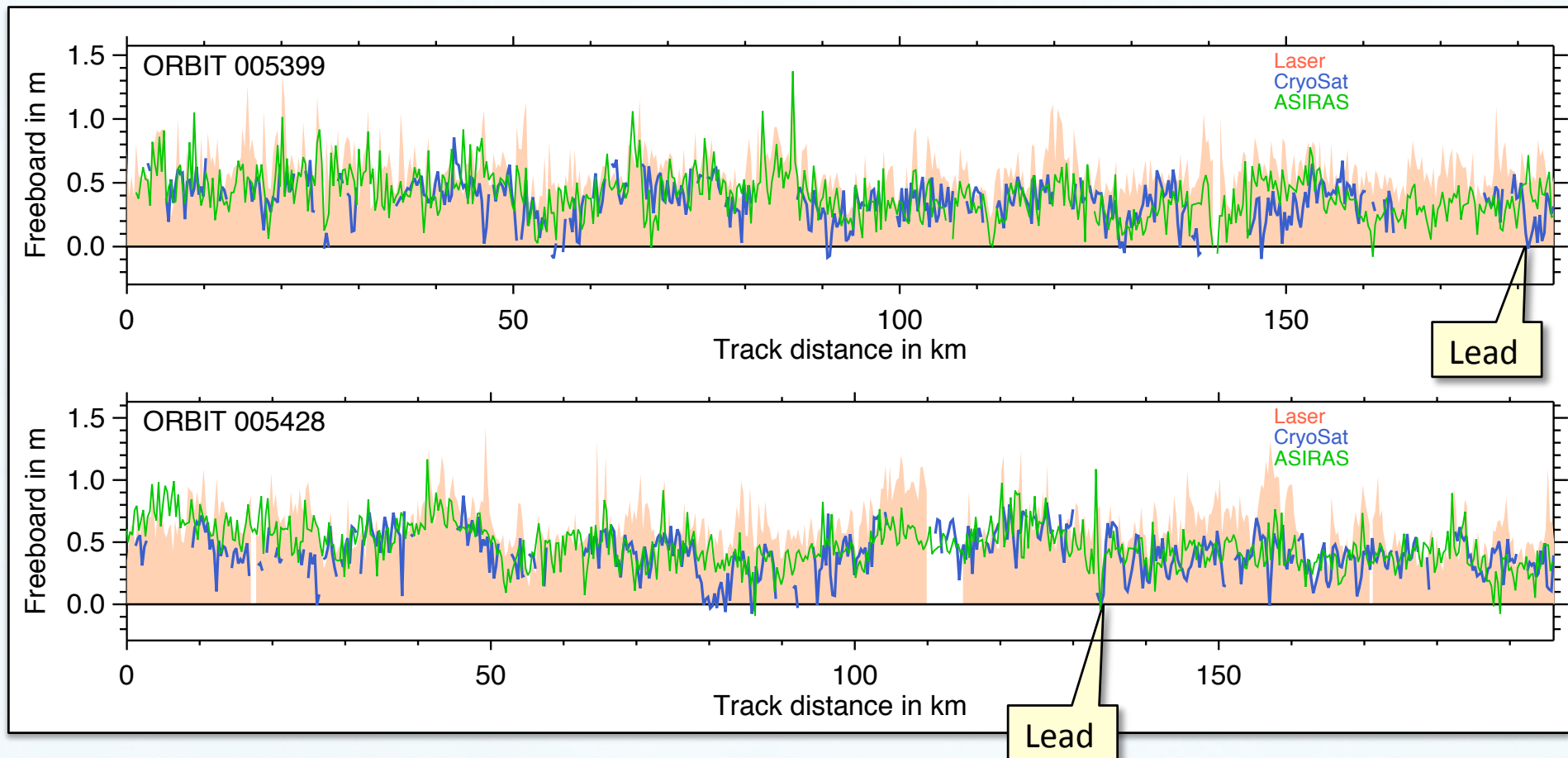
Laser scanner measuring points

CryoSat-2 footprint

ASIRAS footprint

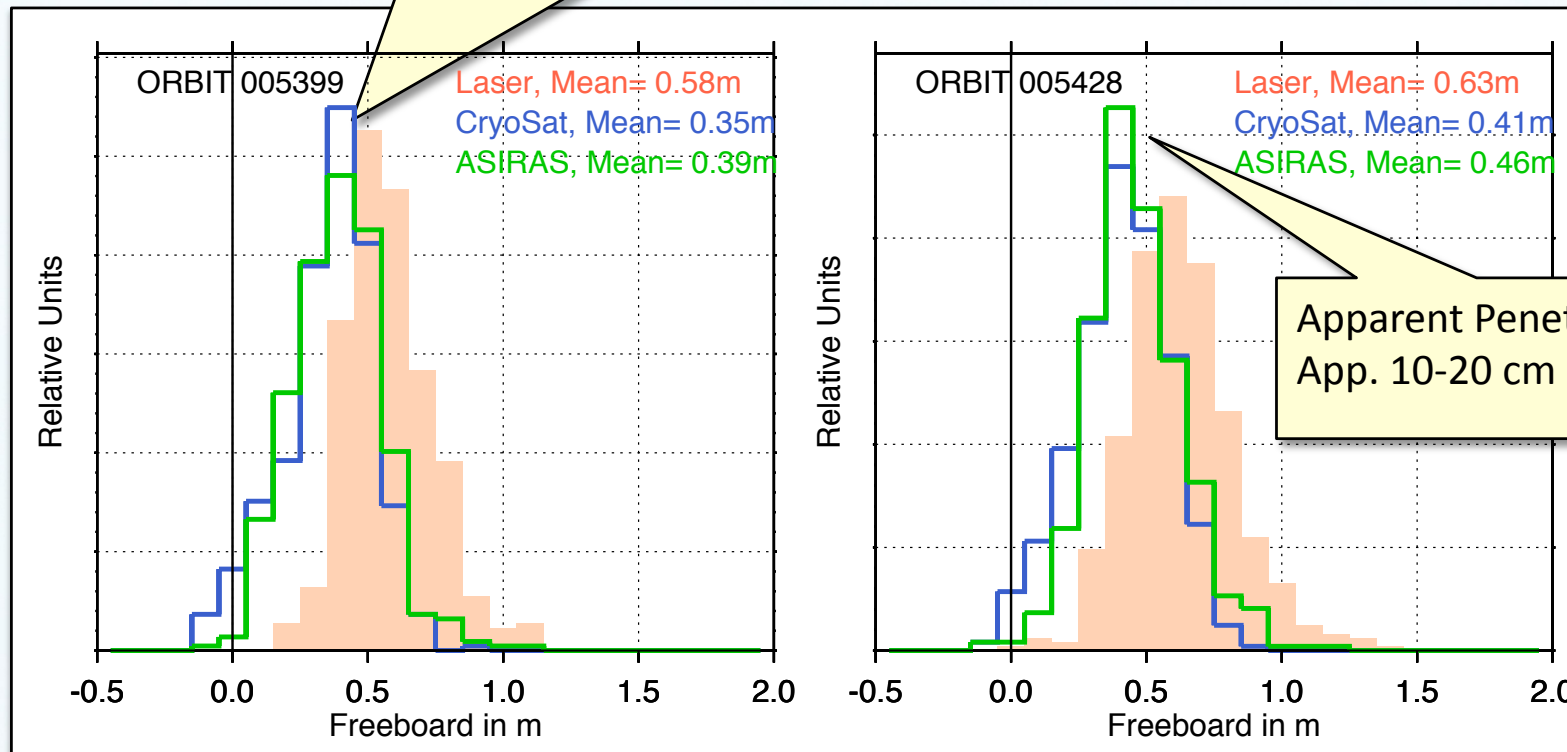
Averaged laser and ASIRAS elevation

Results: Sea-ice freeboard along track



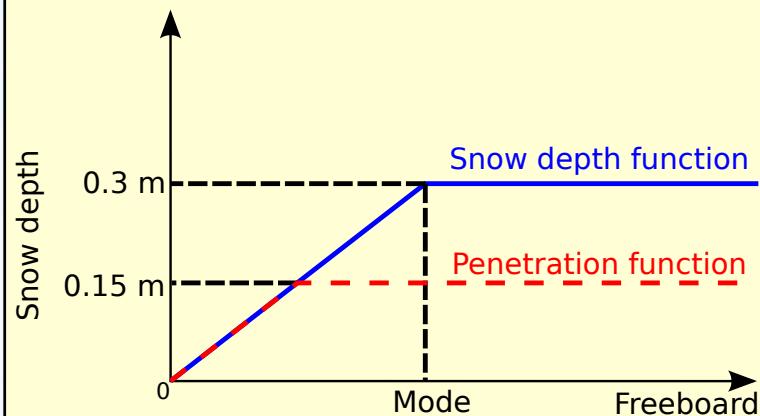
Sea-ice freeboard distribution

Radar modal freeboard is shifted to lower values compared to the Laser freeboard which indicates a penetration of the K_u band signal.



Calculating sea-ice thickness

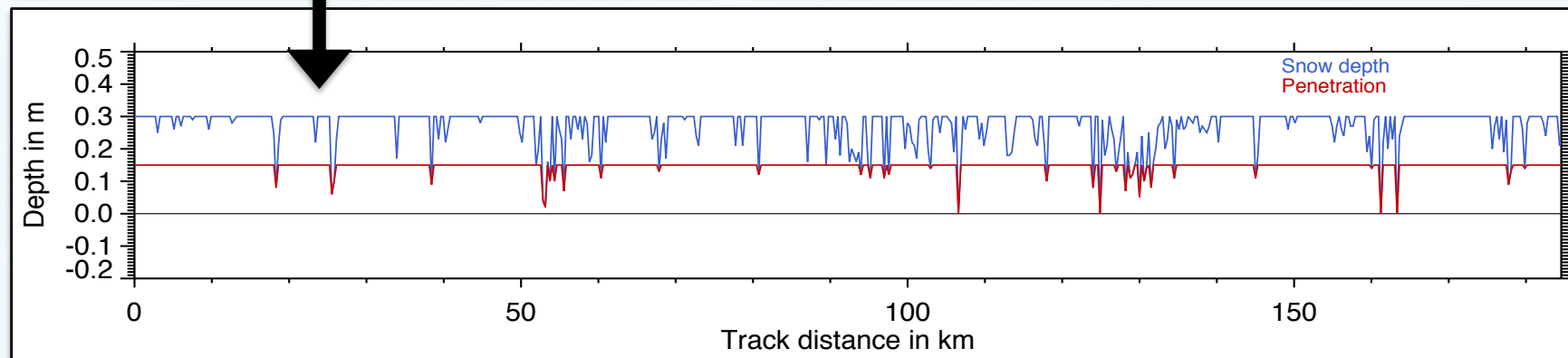
Assumed snow depth function:



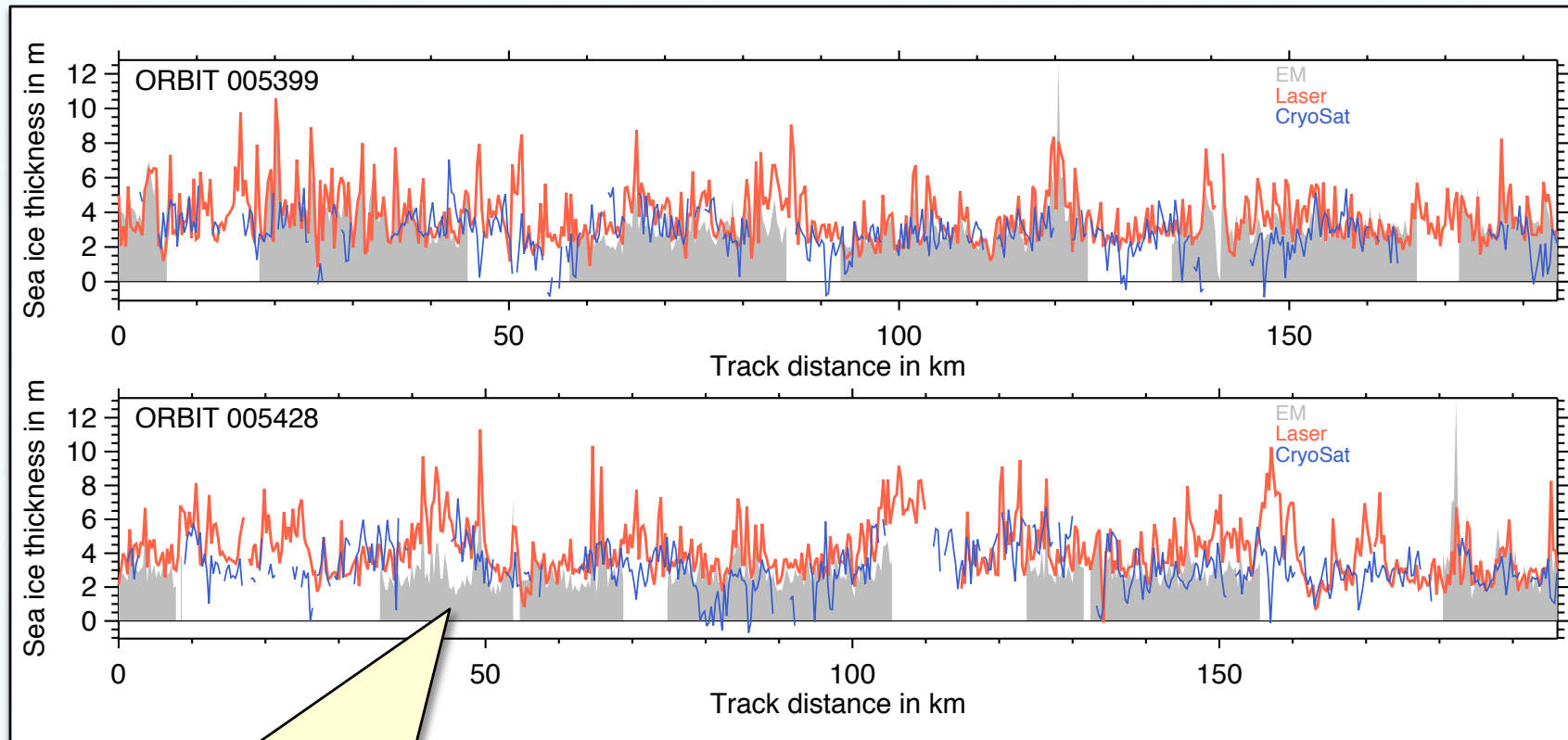
Sea-ice thickness T (with penetration term):

$$T = F \cdot \frac{\rho_W}{\rho_W - \rho_I} + Z \cdot \frac{\rho_S - \rho_W}{\rho_W - \rho_I} + P \cdot \frac{\rho_W}{\rho_W - \rho_I}$$

- F Freeboard
- Z Snow depth
- P Penetration
- ρ_W Water density: 1020 kg/m³
- ρ_I Ice density: 910 kg/m³
- ρ_S Snow density: 300 kg/m³



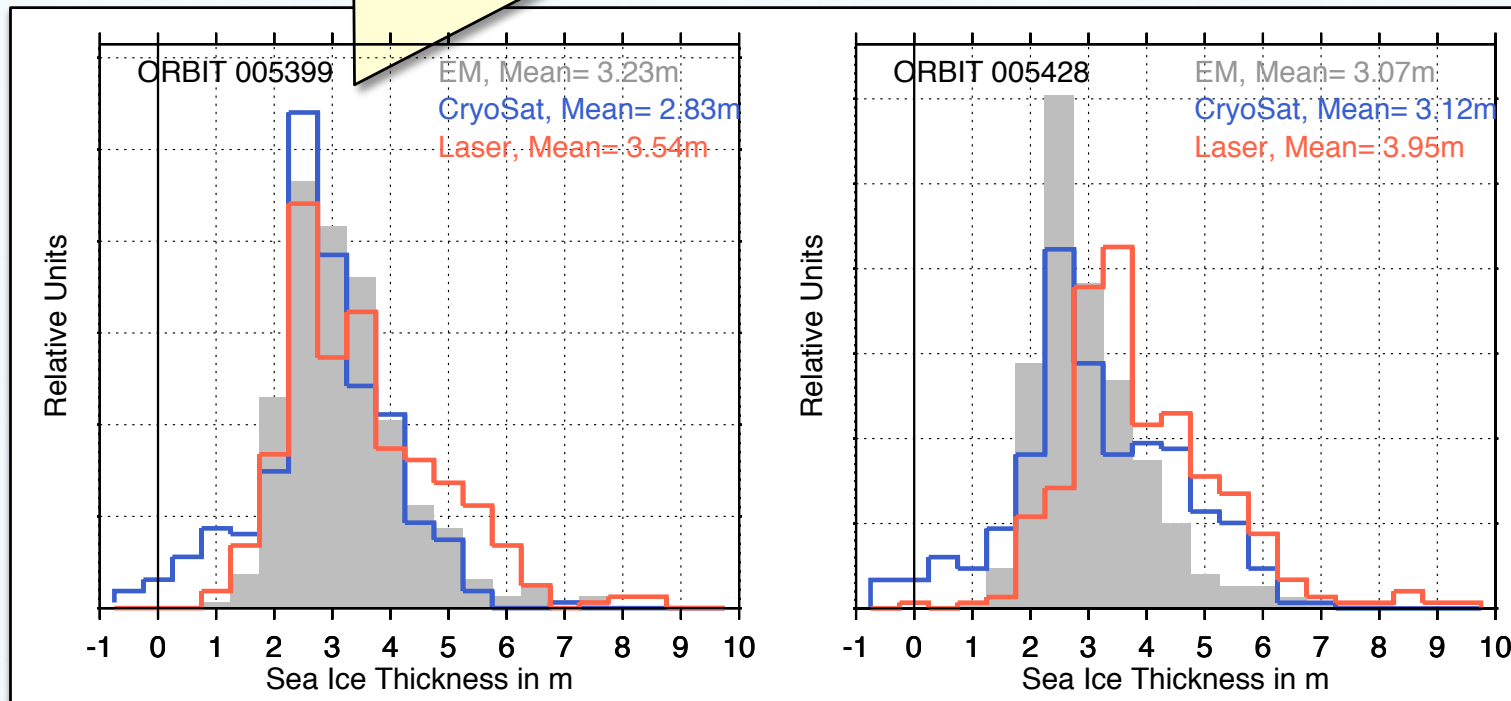
Results: Sea-ice thickness along track



Direct thickness measurements from
electromagnetic induction sounding (EM Bird)

Sea-ice thickness distribution

Using the assumed density values, snow depth and penetration provide a good agreement with the direct thickness measurements from electromagnetic induction sounding



Conclusion and outlook

- CryoSat-2 freeboard generally coincides with the ASIRAS freeboard.
- Radar does not penetrate the snow cover completely.
- With an assumed snow depth of 0.3 m and a penetration of 0.15 m a good agreement between Laser, radar and EM sounding thickness retrieval is achieved.

Outlook: We will investigate the influence of a snow layer and surface roughness with a forward model for CryoSat-2 waveforms.

Acknowledgements

The measurements in the framework of CryoVEx and PAM-ARCMIP 2011 campaigns were carried out by the DTU Space and the Alfred Wegener Institute for Polar and Marine Research. The CryoVEx campaigns are part of ESA's Living Planet Programme. The CryoSat-2 data are provided by the ESA. All this is gratefully acknowledged.

THANK YOU