

Cloud phase identification of Arctic boundary-layer clouds from airborne spectral reflection measurements: test of three approaches

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Abstract. Arctic boundary-layer clouds were investigated with remote sensing and in situ instruments during the Arctic Study of Tropospheric Aerosol, Clouds and Radiation (ASTAR) campaign in March and April 2007. The clouds formed in a cold air outbreak over the open Greenland Sea. Beside the predominant mixed-phase clouds pure liquid water and ice clouds were observed. Utilizing measurements of solar radiation reflected by the clouds three methods to retrieve the thermodynamic phase of the cloud are introduced and compared. Two ice indices I_S and I_P were obtained by analyzing the spectral pattern of the cloud top reflectance in the near infrared (1500–1800 nm wavelength) spectral range which is characterized by ice and water absorption. While I_S analyzes the spectral slope of the reflectance in this wavelength range, I_P utilizes a principle component analysis (PCA) of the spectral reflectance. A third ice index I_A is based on the different side scattering of spherical liquid water particles and nonspherical ice crystals which was recorded in simultaneous measurements of spectral cloud albedo and reflectance.

Radiative transfer simulations show that I_S , I_P and I_A range between 5 to 80, 0 to 8 and 1 to 1.25 respectively with lowest values indicating pure liquid water clouds and highest values pure ice clouds. The spectral slope ice index I_S and the PCA ice index I_P are found to be strongly sensitive to the effective diameter of the ice crystals present in the cloud. Therefore, the identification of mixed-phase

clouds requires a priori knowledge of the ice crystal dimension. The reflectance-albedo ice index I_A is mainly dominated by the uppermost cloud layer ($\tau < 1.5$). Therefore, typical boundary-layer mixed-phase clouds with a liquid cloud top layer will be identified as pure liquid water clouds. All three methods were applied to measurements above a cloud field observed during ASTAR 2007. The comparison with independent in situ microphysical measurements shows the ability of the three approaches to identify the ice phase in Arctic boundary-layer clouds.

1 Introduction

The impact of clouds on the radiation budget of Arctic regions constitutes a crucial uncertainty in predicting Arctic climate change as reported in the Arctic Climate Impact Assessment (Corell, 2004). In most cases Arctic clouds warm the atmosphere (Intrieri et al., 2002). Due to the high albedo of the snow- or ice-covered surfaces the longwave radiative heating dominates over the solar cooling and thus determines the cloud radiative forcing in the Arctic. Shupe and Intrieri (2004) have shown that low-level clouds are the most important contributors to the Arctic surface radiation budget. Their radiative impact is highly variable and depends on surface albedo, aerosol particles, cloud water content, cloud particle size and cloud thermodynamic phase (Curry et al., 1996; Shupe and Intrieri, 2004).

For example, a low surface albedo in summer leads to a seasonal cooling effect of Arctic clouds (Dong and Mace, 2003). For marine clouds, Freese and Kottmeier (1998) have



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found that the low surface albedo of the ice-free ocean reduces the upwelling radiation above the clouds and thus the cloud albedo by up to 30% compared to clouds over highly reflecting sea ice. Cloud radiative properties and cloud life cycle are also influenced by the cloud thermodynamic phase (Sun and Shine, 1994; Harrington et al., 1999; Yoshida and Asano, 2005; Ehrlich et al., 2008b). The simulations by Harrington et al. (1999) have shown that the cloud top temperature and the amount of ice nuclei control the conversion of liquid cloud water to solid ice. Cold temperatures and high ice nuclei concentrations lead to a higher ice fraction and a shorter life time of the mixed-phase clouds. Furthermore, Yoshida and Asano (2005) have found that an increasing ice fraction results in a significant increase in the absorptance of mixed-phase clouds in the near infrared wavelength range (700–2500 nm).

Therefore, in situ measurements and/or remote sensing of the thermodynamic cloud phase are of importance. Parameterizations of the dependence of ice volume fraction (ratio of ice to total water content) on cloud temperature have been obtained from in situ measurements by Boudala et al. (2004); Korolev et al. (2003). However, due to the limitations in time and space in situ measurements can only give a snapshot of the complexity of Arctic clouds (Lawson et al., 2001; Cober et al., 2001; McFarquhar et al., 2007).

Several cloud retrieval algorithms for different satellite sensors provide the cloud phase. Commonly, before retrieving cloud properties a preselection algorithm distinguishes between ice, mixed-phase and liquid water clouds (Key and Intrieri, 2000; King et al., 2004; Kokhanovsky et al., 2006). This phase discrimination is often based on two methods using the brightness temperatures of thermal infrared (IR; 5–50 μm) channels and the cloud reflectance at channels for near infrared wavelength range (NIR, 700–2500 nm). Further methods are based on radar data (CloudSat, Sassen and Wang, 2008) and polarization measurements, for example using data of the POLarization and Directionality of the Earth's Reflectances instrument (POLDER, Buriez et al., 1997).

The contrast of brightness temperatures measured at two wavelengths is related to the ice volume fraction due to the different emissivity of ice and liquid water at wavelengths larger than 10 μm . Similarly, the cloud reflectance at NIR wavelengths is affected by the different refractive indices (in particular the imaginary part, i.e. absorption index) of ice and liquid water as demonstrated by Pilewskie and Twomey (1987). Therefore, the ratio of cloud reflectances at two wavelengths can be used to determine the cloud thermodynamic phase (band ratio method). Both methods were compared by Chylek et al. (2006) for the Moderate Resolution Imaging Spectroradiometer (MODIS) showing significant discrepancies between the results of the two methods with a tendency of an overestimation of ice clouds by the band ratio method. The authors suggest to use the ratio of highly resolved NIR spectral bands around 1.5 and

1.4 μm . This has successfully been applied by Knap et al. (2002) and Acarreta et al. (2004) for the Airborne Visible and Infrared Imaging Spectrometer (AVIRIS) and the Scanning Imaging Absorption Spectrometer for Atmospheric CHarotographY (SCIAMACHY).

In this study we present similar methods of cloud phase identification using airborne measurements of spectral solar cloud reflectance combined with radiative transfer simulations. Three approaches to discriminate the cloud phase are applied and discussed. First results applying these methods have been published in Ehrlich et al. (2008a). The measurements presented here were performed during the Arctic Study of Tropospheric Aerosol, Clouds and Radiation (ASTAR) 2007 campaign. Additional information on cloud phase was obtained from in situ cloud microphysical and airborne lidar measurements.

The instrumentation of the aircraft is described in Sect. 2. The measurements of spectral cloud reflectance and three methods to obtain information on the cloud phase are discussed in Sects. 3 and 4. Subsequently, the three methods are analyzed by sensitivity studies in Sect. 5. Finally, in Sect. 6 the application of the methods is examined by a case study of observations from 7 April 2007.

2 Instrumentation

During ASTAR 2007 two aircraft were employed. We report on data from the Polar 2 aircraft, owned by the Alfred Wegener Institute for Polar and Marine Research (AWI), Bremerhaven, Germany. The airborne instrumentation included the Spectral Modular Airborne Radiation measurement system (SMART-Albedometer), in situ instruments such as the Polar Nephelometer, Cloud Particle Imager (CPI), and Particle Measuring System (PMS) Forward Scattering Spectrometer Probe (FSSP-100), and the Airborne Mobile Aerosol Lidar (AMALi).

The SMART-Albedometer was developed at the Leibniz-Institute for Tropospheric Research, Leipzig, Germany as a modular system to measure solar spectral radiation (radiance, irradiance, actinic flux density) from airborne platforms as described, e.g., by Wendisch and Mayer (2003); Wendisch et al. (2004); Jäkel et al. (2005); Bierwirth et al. (2009). The optical inlets for separate detection of upwelling and downwelling radiation are actively leveled to compensate deviations of the aircraft attitude from the horizontal plane (Wendisch et al., 2001). The configuration of the SMART-Albedometer operated during ASTAR 2007 provides measurements of downwelling and upwelling spectral irradiances (F_{λ}^{\downarrow} , F_{λ}^{\uparrow}) simultaneously with upwelling nadir spectral radiance (I_{λ}^{\uparrow}). The downwelling irradiance presented here includes diffuse and direct solar radiation and is measured with respect to a horizontal plane $F_{\lambda}^{\downarrow} = F_{\lambda}^{\downarrow}(\cos \theta)$ with θ giving the solar zenith angle.

Two spectrometer systems have been applied to measure F_{λ}^{\downarrow} and I_{λ}^{\uparrow} at the visible and near infrared wavelengths. The spectrometer systems cover the spectral wavelength range 350–950 nm and 950–2100 nm with a spectral resolution (full width at half maximum) of 2–3 nm and 9–16 nm, respectively. F_{λ}^{\uparrow} was measured in the visible part of the spectrum only (350–950 nm). The optical inlets for the irradiance measurements (constructed by the Bay Area Environmental Research Institute, CA, USA) are designed as integrating spheres made of Spectralon reflectance material (Crowther, 1997). Sealed with a quartz dome, the Spectralon integrating sphere provides an almost wavelength-independent photon collection efficiency. To measure I_{λ}^{\uparrow} a set of new optical inlets for radiance measurements has been constructed. The entrance optics of the radiance optical inlet is based on a Zeiss collimator lens (BK 7 glass) with a focal length of 31.6 mm. The collimator is mounted within a cylindrical housing that reduces stray light. Two apertures at both ends of the housing define the angle of view. Laboratory measurements and ray tracing simulations found an angle of view of 2.1°. The outer aperture is covered by BK 7 glass providing vacuum conditions inside the tube and protection against condensation during changes of the external temperature conditions.

The in situ measurements of cloud microphysical properties include particle number size distribution in the size range of 3–27 μm for the FSSP and 23–2300 μm for the CPI, extinction coefficient, ice and liquid water content, effective diameter, scattering phase function and the asymmetry parameter, a measure for the anisotropy of the scattering phase function. The instruments, data retrieval and measurement uncertainties are described by Gayet et al. (2007).

Additional independent information on the cloud phase was provided by the depolarization measurements of AMALi which is a two-wavelength (532 nm and 355 nm) backscatter lidar with depolarization measurements at 532 nm wavelength. AMALi was installed in nadir-looking configuration. The vertical resolution was 7.5 m; the minimum horizontal resolution was about 900 m. Further details of AMALi are described in Stachlewska et al. (2004).

3 Measurements

3.1 Synoptic situation

We concentrate on a special period during ASTAR 2007 (7–9 April) which was characterized by a cold air outbreak. The northerly winds initiated extended boundary-layer cloud fields over the open Greenland Sea as shown by the MODIS satellite image in Fig. 1. The convection above the relatively warm open sea maintained the coexistence of ice and liquid water particles in the clouds. Detailed investigations on the self-maintaining dynamics of the mixed-phase clouds are described by Harrington et al. (1999); Fridlind et al. (2007);

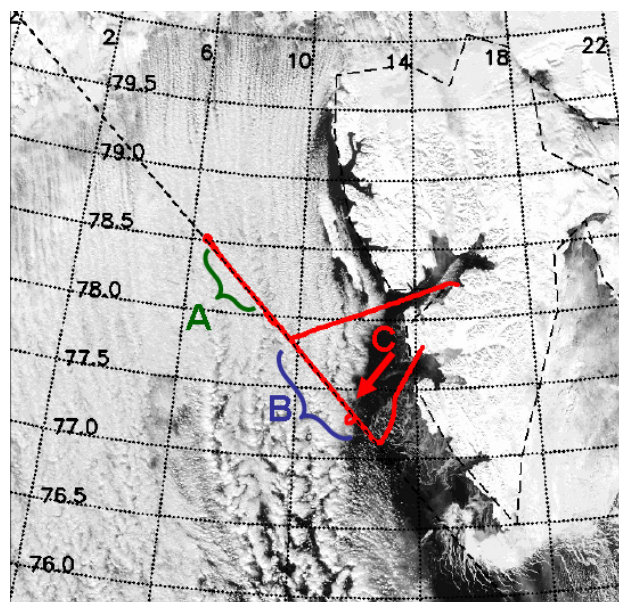


Fig. 1. MODIS satellite image of 7 April 2007 overlaid with the flight track of Polar 2 aircraft (red line) along the CALIPSO overpass (dashed black line). The numbers give the latitude (North) and longitude (East of Greenwich). Flight sections where measurements are analyzed are marked with labels A, B and C. At A a mixed-phase cloud was sampled by both in situ instruments and the SMART-Albedometer, at C a pure ice cloud was observed with the SMART-Albedometer only (cf. Sect. 3). The flight section B is analyzed with regard to cloud thermodynamic phase in Sect. 6.

Morrison et al. (2008). In addition to the predominating mixed-phase clouds, pure ice and pure liquid water clouds were observed during this period of ASTAR 2007 providing the possibility to test cloud phase identification methods.

3.2 In situ measurements

In situ measurements have been obtained from a total of 16 vertical profiles flown between 7–9 April. Except for two profiles taken at the edge of the cloud fields where pure ice clouds were observed, the in situ measurements generally show the typical structure of the prevailing mixed-phase clouds with a cloud top layer consisting of liquid water and precipitating ice crystals below. Based on in situ data, the particle phase was determined from the combination of asymmetry parameter and particle concentration measurements. The asymmetry parameter is significantly lower for nonspherical ice crystals than for spherical liquid water particles (e.g., Gerber et al., 2000; Garrett et al., 2001). As an approximation the FSSP size range (3–27 μm) is defined to measure liquid water particles whereas the CPI (23–2300 μm) is used to determine the size distribution of large ice crystals. An analysis of the combined particle concentration and asymmetry parameter measurements (not shown here) confirms, that this assumption works sufficiently

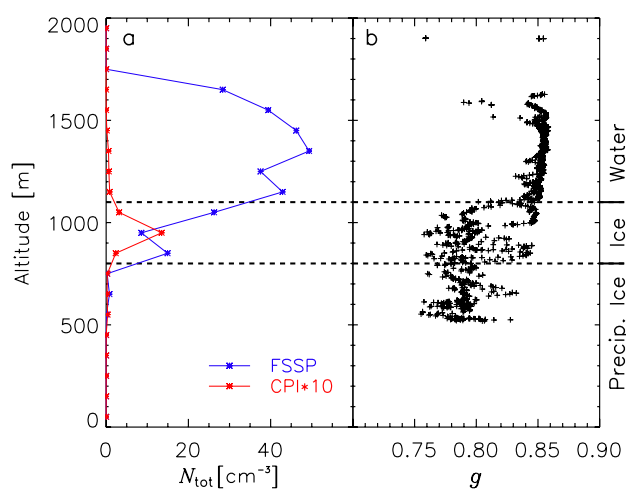


Fig. 2. Profiles of microphysical measurements on 7 April 2007. Total particle concentrations N_{tot} measured by FSSP and CPI are given in panel a. The asymmetry parameter g obtained from the Polar Nephelometer is shown in panel b.

well for the mixed-phase clouds encountered during ASTAR 2007.

A typical profile of measured particle concentration and asymmetry parameter obtained on 7 April between 78.0° N and 78.5° N (cp. Fig. 1 label A) is presented in Fig. 2. The FSSP indicated particle concentrations up to $N_{\text{tot}}=50 \text{ cm}^{-3}$ between 1000–1700 m altitude. In the same layers the asymmetry parameter measured by the Polar Nephelometer, was about 0.85 which is a typical value for liquid water droplets (e.g., Gerber et al., 2000; Garrett et al., 2001). A thin layer dominated by ice crystals was found between 800 m and 1100 m, indicated by lower asymmetry parameters. In this layer the CPI measured particle concentrations of up to $N_{\text{tot}}=1.5 \text{ cm}^{-3}$ with maximum particle dimensions of up to 1000 μm . Below this layer, precipitating large ice particles were observed down to 500 m by visual observation on board the aircraft and from in situ measurements indicating a low particle concentration (CPI and FSSP) and a low asymmetry parameter measured by the Polar Nephelometer.

The profile of asymmetry parameter presented in Fig. 2b shows a distinct transition between high values related to liquid water droplets and low values related to ice crystals. Only a few measurements show intermediate values. As Garrett et al. (2001) have shown the asymmetry parameter measured in Arctic stratus changes linearly from 0.86 to 0.76 depending on the fractional number of particles in the cloud that are ice rather than liquid. Therefore, the measurements presented in Fig. 2b reveal that liquid water droplets are dominant in the upper cloud layer and ice crystals characterize the optical properties of the lower cloud layers.

The mean effective diameters of ice crystals and liquid water particles averaged over the in situ measurements of the entire cloud amounts to $(85 \pm 37) \mu\text{m}$ for ice crystals (CPI) and $(15 \pm 5) \mu\text{m}$ for liquid water particles (FSSP). The cloud optical thickness estimated from the measured extinction coefficients from the FSSP and CPI was about 15–20.

3.3 Airborne lidar measurements

The laser of the AMALi lidar did not completely penetrate the optically thick clouds. However, AMALi did identify a liquid water layer at cloud top by the depolarization signal. Although multiple scattering in the liquid water layer generated high depolarization values, comparable to the depolarization signal of ice crystals, the detailed analysis of the lidar profiles averaged over 15 s reveals differences in the vertical pattern of the depolarization. The depolarization related to multiple scattering of liquid water particles increases slowly with cloud depth whereas nonspherical ice crystals result in an instantaneous increase of the depolarization (Hu et al., 2007). From this analysis the precipitating ice below the clouds was identified in several cloud gaps.

3.4 Cloud top reflectance

Spectral cloud top reflectances R were calculated from the SMART-Albedometer radiance and irradiance measurements,

$$R_{\lambda} = \pi \cdot I_{\lambda}^{\uparrow} / F_{\lambda}^{\downarrow}. \quad (1)$$

Beside the typical mixed-phase clouds also pure ice and pure liquid water clouds were observed during ASTAR 2007. Cloud top reflectances for exemplary samples of all three measured cloud types are shown in Fig. 3a. The mixed-phase and ice clouds were observed during the first flight on 7 April as indicated by the labels A and C in Fig. 1. Measured microphysical properties of the mixed-phase cloud are discussed in Sect. 3.2. The water cloud was sampled during a second flight on 7 April between 75.4° N, 11.5° E and 75.8° N, 11.8° E. All measurements shown here are averaged over the time period the cloud was sampled (mixed-phase cloud 18 min, water cloud 8 min and ice cloud 2 min). Especially the liquid water cloud shows differences of R_{λ} in the wavelength range between 500 nm and 1300 nm as shown in Fig. 3a. These differences result from different cloud optical thickness τ . We retrieved τ for the clouds presented here by applying standard retrieval techniques (Nakajima and King, 1990). The mixed-phase cloud assumed as liquid water cloud for the retrieval has a τ of 12, while for the ice and pure liquid water cloud $\tau=4$ and $\tau=15$ was found, respectively.

In the wavelength range 1450–1750 nm where R_{λ} depends less of τ the cloud top reflectances reveal significant differences in the spectral pattern. These differences are caused by the contrast in the imaginary part n_i of the refractive index (absorption index) of ice and liquid water shown in Fig. 3b.

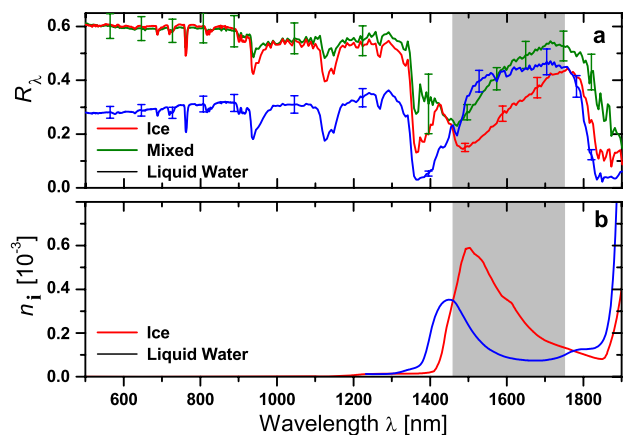


Fig. 3. Examples of measured cloud top reflectance R_λ (7 April 2007) over a pure ice cloud ($\tau=12$), pure liquid water cloud ($\tau=4$) and mixed-phase cloud ($\tau=15$) are given in panel a. Error bars indicate the measurement uncertainty of the reflectance measurements. Panel b shows the imaginary part n_i of the refractive index for ice and liquid water.

Of all clouds, pure liquid water clouds show the highest R_λ values at 1500 nm where the difference of ice and liquid water absorption is maximum. The slope of the reflectance between 1500 nm and 1750 nm is small for liquid water clouds and larger for pure ice clouds. These differences in the spectral pattern of R_λ can be used to remotely discriminate the cloud phase.

The thermodynamic phase of the ice and mixed-phase clouds presented here has been verified independently by the in situ measurements as described in Sect. 3.2. The ice cloud is investigated in a case study described in Sect. 6.

4 Definition of ice indices: three approaches

To define three ice indices characterizing the cloud thermodynamic phase and to evaluate their sensitivity to cloud optical properties we have performed radiative transfer simulations for pre-defined pure ice and pure liquid water boundary-layer clouds of varying optical thickness ($\tau=2/4/6/8/10/12/14/16/18/20$) and effective diameter D_{eff} . For liquid water clouds the effective diameter was varied to 8/10/14/20/26 μm corresponding to the range reported by Miles et al. (2000) for marine stratocumulus clouds. The ice clouds have been modeled for the range of effective diameter observed during ASTAR 2007 (30/60/90/120/150 μm).

The spectral solar radiative transfer simulations are performed with the libRadtran (Library for Radiative transfer) code by Mayer and Kylling (2005) for the wavelength range from 300 nm to 2200 nm adapted to the spectral resolution of the SMART-Albedometer. The discrete ordinate solver DISORT version 2.0 by Stamnes et al. (1988) is applied.

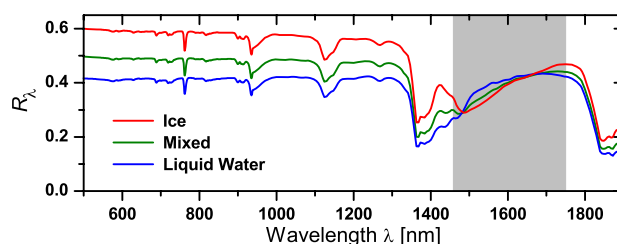


Fig. 4. Examples of simulations of cloud top reflectance R_λ for pure ice, pure liquid water and mixed-phase clouds with optical thickness of 12.

The meteorological input (profiles of static air temperature, relative humidity and static air pressure) is obtained from a radio sounding at Ny Ålesund/Svalbard (7 April 2004, 11:00 UTC). Corresponding to the observed marine clouds, the spectral surface albedo is represented by measurements above sea water obtained during ASTAR 2007.

For the radiative transfer simulations a stratiform cloud layer was situated between 750 m and 1750 m altitude above the sea surface. The spectral cloud optical properties (extinction coefficient, single scattering albedo and scattering phase function) have been calculated from optical properties of the individual cloud particles. Mie theory is applied for liquid water droplets. For the ice particles column-shaped ice crystals have been assumed. The optical properties of columns have been provided by Yang and Liou (1996). For the simulations presented here the choice of the particle shape is of less importance. With regard to the wavelength range where ice absorption occurs, the predetermined effective diameter of the cloud particles characterizes the absorption independent of the particle shape. For the reflectance at visible wavelengths the scattering phase function of the ice crystals is crucial. However, the part of the scattering phase function relevant for the solar zenith angles observed during ASTAR 2007 is similar for different ice crystal shapes as shown below in Sect. 4.3 and Fig. 8.

Results of the radiative transfer simulations for clouds comparable to the observed ice, liquid water and mixed-phase clouds ($\tau=12$) are given in Fig. 4. To illustrate the spectral differences between 1450 nm and 1750 nm the effective diameter of the ice crystals (20 μm) and liquid water droplets (10 μm) used in the simulations has been chosen to yield a similar magnitude of R_{1600} . The mixed-phase cloud was simulated as a single-layer homogeneous mixed cloud with an ice volume fraction of 0.5. The simulations of R_λ show a similar spectral pattern in the wavelength range 1450–1750 nm compared to the measurements of the three cloud types (Fig. 3a) with the steepest slope observed for the ice cloud. For wavelengths shorter than 1300 nm, R_λ differs in the simulations because of the different scattering phase functions of ice (nonspherical shape) and liquid water particles (spherical shape).

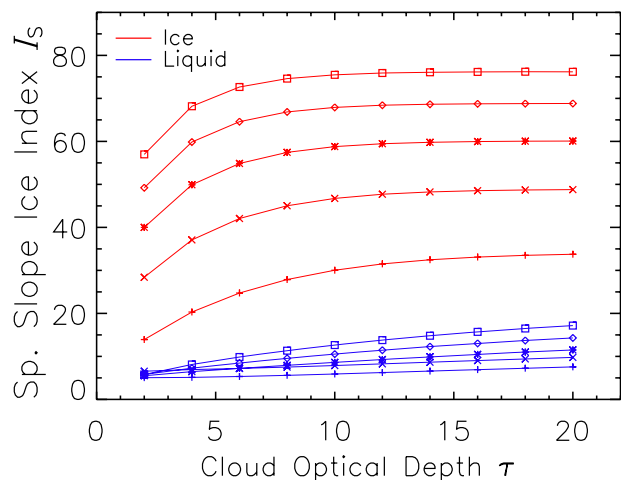


Fig. 5. Spectral slope ice index I_S calculated from simulations of pure ice clouds (red) and pure liquid water clouds (blue). The different D_{eff} are marked by different symbols, plus ($D_{\text{eff}}=30/8\mu\text{m}$), cross ($D_{\text{eff}}=60/12\mu\text{m}$), star ($D_{\text{eff}}=90/16\mu\text{m}$), diamond ($D_{\text{eff}}=120/20\mu\text{m}$), square ($D_{\text{eff}}=150/26\mu\text{m}$).

The characteristics of the reflectance spectra are used in the following three approaches to retrieve the cloud phase from the measurements. A known two-wavelengths approach (Sect. 4.1) and a principle component analysis (Sect. 4.2) was applied. A third approach used the combined albedo and reflectance measurements to obtain information on the cloud phase (Sect. 4.3).

4.1 Spectral slope ice index

The spectral slope of the cloud reflectance between 1640 nm and 1700 nm has been used to identify the cloud phase with AVIRIS by Knap et al. (2002). The dimensionless ice index, defined as

$$I_S^{\text{Knap}} = \frac{R_{1700} - R_{1640}}{R_{1640}} \cdot 100, \quad (2)$$

vanishes for pure liquid water clouds and reaches values of up to 30 for pure ice clouds. For SCIAMACHY Acarreta et al. (2004) have increased the wavelength range used for determination of the spectral slope to 1550–1670 nm. The spectral slope is calculated by linear regression excluding the absorption bands of CO_2 (1560–1580 nm and 1595–1610 nm). Ice indices calculated this way range between 10 for liquid water clouds and 50 for ice clouds.

The wavelength range used by Acarreta et al. (2004) was limited to 1670 nm due to technical characteristics of SCIAMACHY with a change of the spectral resolution at 1670 nm. For our measurements with the SMART-Albedometer the

Table 1. Ice indices I_S , I_P and I_A calculated for the observed clouds presented in Fig. 3a.

	liquid water	mixed	ice
I_S	8.8	29.8	57.0
I_P	0.1	2.3	5.0
I_A	*	1.16	1.36

definition of ice index I_S is extended to the wavelength range between $\lambda_a=1550$ nm and $\lambda_b=1700$ nm,

$$I_S = \frac{100}{R_{1640}} \left[\frac{dR_\lambda}{d\lambda} \right]_{[\lambda_a, \lambda_b]} \quad (3)$$

This is the maximum wavelength range where water vapor absorption does not contribute significantly to the measured signal. To reduce the impact of noise from the individual wavelength channels the slope of R_λ was calculated by linear regression.

The ice indices I_S calculated from the three cloud cases presented in Fig. 3a are given in Table 1. The values range from 8.8 for the liquid water cloud to 57 for the ice cloud with the mixed-phase cloud in-between. These significant differences in I_S confirm that the three observed clouds (pure ice, pure liquid water and mixed-phase) can be distinguished with this method. I_S calculated from the simulated ice and liquid water clouds is shown in Fig. 5. Typical values for liquid water clouds range between $I_S=5$ and $I_S=15$. Ice clouds show a higher variability of I_S with values of up to 80.

4.2 PCA ice index

Principle component analysis (PCA) provides a powerful tool to understand the variations in a multivariate data set (Pearson, 1901). The transformation of the original data into a set of principle components compresses the information given by the multivariate data to a few principle components. Analyzing spectral atmospheric radiation measurements the obtained principle components are correlated with physical processes like molecular scattering, trace gas absorption or aerosol interaction (Rabbette and Pilewski, 2001). We utilize PCA to extract the ice and liquid water absorption signature in measurements and simulations of the spectral cloud top reflectance.

PCA was applied separately on the simulated pure ice and pure liquid water boundary-layer clouds introduced above. For the simulations all effective diameters are taken into account for the PCA, providing a set of 50 different ice and liquid water clouds. The simulated cloud top reflectance was normalized by R_{860} to eliminate the impact of cloud optical thickness. To focus on the ice and liquid water absorption signature only, the wavelength range between $\lambda_1=1500$ nm and $\lambda_2=1800$ nm was considered for the calculations. Finally, the principle components PC_i are calculated

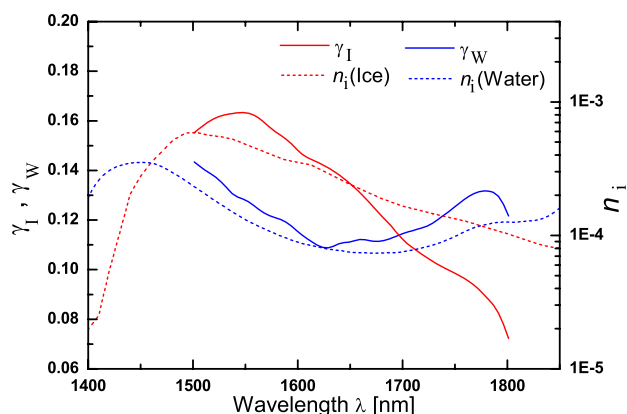


Fig. 6. Component weightings γ_I and γ_W for the calculation of the principle components PC_I and PC_W (solid lines). Dashed lines represent the imaginary part n_i of refractive index for ice and liquid water published by Warren (1984) and Wieliczka et al. (1989).

by applying the component weightings γ_i obtained from the PCA as

$$PC_i = \sum_{\lambda=\lambda_1}^{\lambda_2} \gamma_{i,\lambda} \frac{R_\lambda}{R_{860}} \quad i = 1 \dots N, \quad (4)$$

with i defining the order of the principle component and N the number of wavelength channels used in the analysis. Due to the normalization by R_{860} the remaining variance of the data will mainly result from changes in the absorption of the particles which are due to the variation of their effective diameter. Consequently the calculations show that the first principle component derived from the pure liquid water cloud simulations is related to liquid water absorption (hereinafter called PC_W). The contribution of R_λ at individual wavelengths to PC_W is given by the component weightings γ_W shown in Fig. 6. The minimum weight occurs in the wavelengths between 1600 nm and 1700 nm where liquid water absorption is weak as indicated by the imaginary part n_i of the refractive index (dashed line). In the same way the first principle component from the pure ice cloud simulations (hereinafter called PC_I) is correlated with ice absorption and has the maximum component weighting γ_I at wavelengths around 1550 nm. In order to utilize PC_W and PC_I for cloud phase identification, we define a so called PCA ice index I_P as,

$$I_P = \left(\frac{PC_I}{PC_W} - 0.94 \right) \cdot 100. \quad (5)$$

The offset of 0.94 has been determined arbitrarily in order to obtain values close to zero for liquid water clouds. For the observed liquid water cloud presented in Fig. 3a, $I_P=0.1$ was calculated. Values for all three observed clouds are given in Table 1. The results of the analysis of the simulated liquid water clouds shown in Fig. 7 reveal typical values of

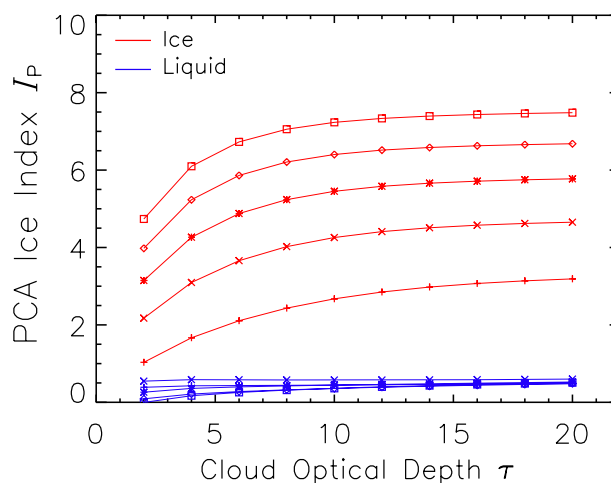


Fig. 7. Same as Fig. 5 for the PCA ice index I_P .

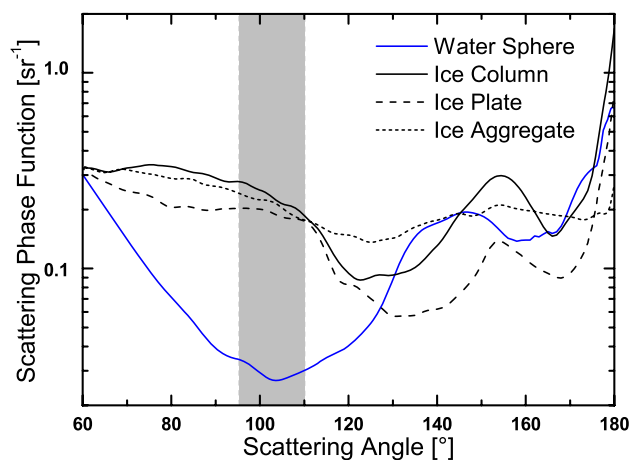


Fig. 8. Scattering phase function of different individual cloud particles at 640 nm wavelength. The diameter of the liquid water sphere is 16 μm . All ice crystals have a maximum dimension of 55 μm .

$I_P=0-1$. For ice clouds I_P ranges from values of 1 up to 8 clearly capable of being distinguished from liquid water clouds. Therefore, I_P is a useful criterium to distinguish ice and liquid water clouds.

4.3 Anisotropy ice index

In general clouds act as non-lambertian reflectors. The radiance field reflected from cloud top is essentially affected by the anisotropic scattering phase function of the cloud particles. Representative scattering phase functions for spherical liquid water particles and ice crystals of column, plate and aggregate shape are illustrated in Fig. 8. Chepfer et al. (2002) used this information to retrieve the ice crystal shape from dual satellite measurements at the wavelength of 650 nm. From the differences in the radiation scattered close to the

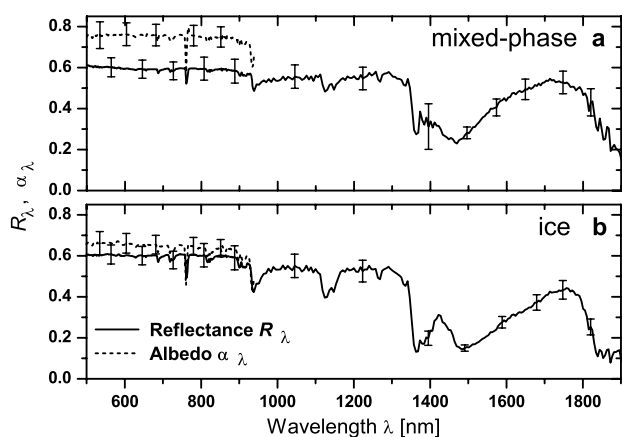


Fig. 9. Cloud top reflectance R_λ and cloud albedo α_λ measured on 7 April 2007, above a mixed-phase cloud (a) of $\tau=15$ and a pure ice cloud (b) of $\tau=12$ introduced in Sect. 3.4 and Fig. 3.

backscatter angle of 180° and those scattered into viewing angles between 60° and 150° particle phase and shape can be distinguished. A similar retrieval of particle phase and shape was applied by McFarlane et al. (2005) to measurements of the Multiangle Imaging Spectroradiometer (MISR) using the nine different viewing angles of the instrument. By minimizing the differences between measured and simulated reflectances they were able to calculate an ice index. It was shown that the highest differences between droplets and crystals occur at scattering angles between 70° and 130° . Both studies emphasize that the retrieved properties are representative only for particles near cloud top.

The configuration of the SMART-Albedometer operating under conditions of low Sun allows for a similar retrieval of the cloud phase using simultaneous albedo and nadir reflectance measurements. With the high solar zenith angles (70° to 85°) during ASTAR 2007, the nadir reflectance measurements correspond to side scattering by the cloud particles with scattering angles of 95° to 110° assuming single scattering as being predominant. As indicated by the grey area in Fig. 8 these scattering angles provide substantially enhanced scattering by nonspherical particles compared to spherical particles. This increases the upwelling radiance and cloud reflectance which is confirmed by simulations for $\theta=71^\circ$ shown in Fig. 4. The pure ice cloud shows higher R_λ at wavelengths up to 1300 nm than the simulations for the pure liquid water cloud. On the other hand, the upwelling irradiance and consequently the albedo $\alpha_\lambda = F_\lambda^\uparrow / F_\lambda^\downarrow$ includes information from all scattering angles and is less dependent on the scattering phase function. This is illustrated in Fig. 9 by comparison of R_λ and α_λ measured above the mixed-phase and pure ice clouds observed on 7 April 2007. Both clouds were observed for $\theta=71^\circ$ and had a comparable optical thickness of 12. The measurements show, that the dif-

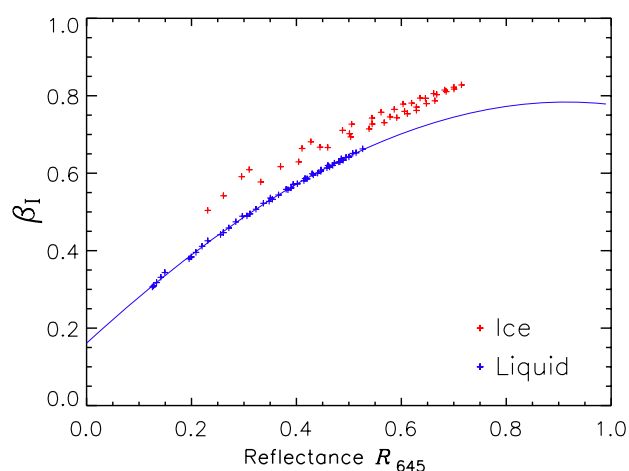


Fig. 10. Simulated β_I for pure liquid water clouds and pure ice clouds (column-shaped crystals) of different optical thickness ($\tau=2-20$) and effective diameter ($8-26 \mu\text{m}$ for liquid water and $10-100 \mu\text{m}$ for ice clouds). The polynomial fit for the liquid water cloud is overlaid as a solid line ($\beta_I=0.15+1.32 \cdot R_\lambda - 0.67 \cdot R_\lambda^2 + 0.01 \cdot R_\lambda^3$).

ference between R_λ and α_λ is smaller for the ice cloud than for the mixed-phase cloud, where liquid water was found at cloud top.

Based on these findings, we suggest the ratio of cloud top reflectance and albedo at 645 nm wavelength $\beta_I = R_{645} / \alpha_{645}$ as an indicator of the anisotropy of the radiation field reflected at cloud top. For the geometry presented here with $\theta=71^\circ$, β_I is always lower than 1 whereby nonspherical particles give a higher β_I than spherical particles. $\beta_I=1$ would mean that the radiation is reflected isotropically, i.e., $\alpha = \pi R$.

With increasing cloud optical thickness both α and R increase with a stronger increase for R . Increased multiple scattering diminishes the information of the scattering phase function and leads to more isotropically reflected radiation. That is why also β_I increases with cloud optical thickness. This relation is plotted in Fig. 10 using R_{645} as a measure of cloud optical thickness on the abscissa. The data result from simulations of pure liquid water clouds and pure ice clouds presented above. Both liquid water and ice clouds show a distinct relation between β_I and R_{645} , with the isotropy of the reflected radiation being significantly higher above ice clouds than above liquid water clouds of the same R_{645} . These differences can be utilized to identify the cloud phase.

Therefore, we have parameterized β_I for the simulated liquid water clouds as function of R_{645} by the polynomial fit shown as a blue solid line in Fig. 10. This parametrization is valid for the assumed geometry (θ , nadir view, flight altitude) and the entire variety of liquid water clouds (τ , D_{eff}) provided by the simulation. This leads us to the definition of the anisotropy ice index I_A as the deviation of the measured β_I^{meas} from the β_I^{water} parameterized for liquid water clouds.

I_A is calculated as the ratio

$$I_A = \frac{\beta_1^{\text{meas}}}{\beta_1^{\text{water}}} \quad (6)$$

Therefore, β_1^{water} is obtained from the polynomial fit using the measured value of R_{645}^{meas} . Using R_{645}^{meas} incorporates indirectly the cloud optical thickness and reduces their impact on I_A . From the definition of I_A it follows that we obtain $I_A=1$ for pure liquid water clouds and $I_A>1$ for pure ice clouds.

The results for the observed pure ice cloud and mixed-phase cloud shown in Fig. 3a are given in Table 1. Both values differ significantly from unity. For the pure liquid water cloud it was not possible to calculate I_A . This cloud had a small horizontal extension. The measured albedo was substantially affected by the dark water surface visible apart the cloud.

Typical values for water clouds obtained from the simulated clouds are shown in Fig. 11 and range between $I_A=0.98$ and $I_A=1.03$. Ice clouds give higher values of $I_A>1.06$ separated distinctly from the results for liquid water clouds.

5 Sensitivity studies

The cloud top reflection (especially in the wavelength range used to calculate the ice indices) is affected not only by the cloud thermodynamic phase but also by other cloud optical properties (cloud optical thickness and cloud particle effective diameter). In order to reduce their impact on the cloud phase retrieval we apply different normalizations of R_λ before calculating the ice indices as shown above. Nevertheless it is impossible to overcome those related uncertainties completely.

Acarreta et al. (2004) have shown for their ice index similar to the spectral slope ice index I_S that the obtained values for ice clouds may vary by a factor of up to 3 between clouds of small effective diameter/low cloud optical thickness and clouds of large effective diameter/high cloud optical thickness. Changes in the solar zenith angle have been found to be less important for the simulated ice indices. Especially for optically thin clouds the surface properties will have an impact on the ice indices. The surface albedo is crucial for the visible wavelength used to calculate the anisotropy ice index I_A while absorption by liquid water, snow or sea ice may affect the spectral slope ice index I_S and the PCA ice index I_P . In order to reduce the complexity in this study we concentrate on the conditions found during ASTAR 2007 with an open sea surface.

In the following we discuss the impact of cloud optical thickness and particle effective diameter on the unambiguity to discriminate pure ice and pure liquid water clouds by the ice indices defined in this paper (Sect. 5.1). Section 5.2 presents investigations of the sensitivity of the ice indices on the vertical structure of mixed-phase clouds.

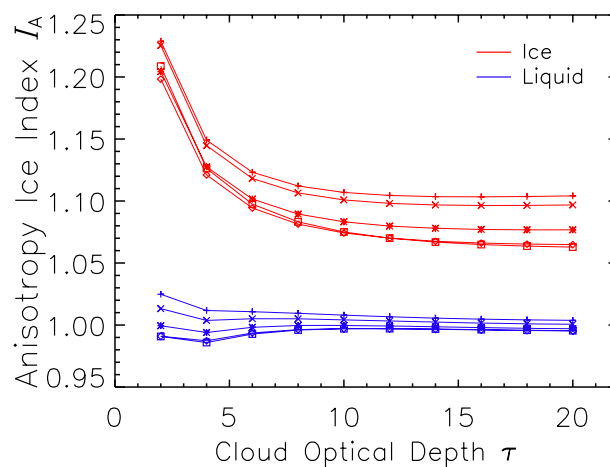


Fig. 11. Same as Fig. 5 for the anisotropy ice index I_A .

5.1 Cloud optical properties

The ice indices I_S , I_P and I_A calculated from the simulations of pure ice and liquid water clouds of different τ and D_{eff} are shown in Figs. 5, 7 and 11. The plots reveal that the ice indices are almost insensitive to D_{eff} and τ for pure liquid water clouds. The values vary only slightly with D_{eff} and τ . The spectral slope ice index I_S and the PCA ice index I_P show almost no variation with τ . On the other hand, the ice indices of the pure ice clouds spread over a wide range. Most significant is the decrease of I_S and I_P with decreasing D_{eff} . Especially for optically thin ice clouds I_S can reach values of pure liquid water clouds with high optical thickness. A slight improvement is given by I_P . Here none of the ice clouds gives values as low as the simulated liquid water clouds. The discrimination of pure ice and pure liquid water clouds is almost unambiguous. With regard to an identification of mixed-phase clouds a priori knowledge of D_{eff} and τ is needed. The ice indices obtained for a mixed-phase cloud range between a minimum value given by a liquid water cloud and a maximum given by an ice cloud with D_{eff} and τ equal to the values of the mixed-phase cloud (not shown here). If D_{eff} , τ and accordingly the maximum values of I_S and I_P are not known, the ice indices obtained for the mixed-phase cloud may indicate a pure ice cloud with smaller D_{eff} or smaller τ .

Most robust with regard to the cloud optical properties of ice crystals is the anisotropy ice index I_A . Figure 11 shows that values for ice and liquid water clouds differ for all simulations. Therefore I_A is most suitable for discriminating ice and liquid water clouds in the setting of the present sensitivity study. It has to be pointed out that theoretically I_A is exactly 1 for the liquid water clouds as the data shown here are simulations equal to the simulations used to parameterize β_1^{water} . The deviation from 1 results from slight differences between data points of β_1^{water} and its parameterization (cp. Fig. 10).

Table 2. I_S , I_P , and I_A of mixed-phase clouds ($\tau_W=13.5$, $\tau_I=1.5$) for different positions of the ice layer (not all 10 simulations shown here). The position is given by the optical thickness τ_W^{top} of the liquid water layer above the single ice layer.

τ_W^{top}	I_S	I_P	I_A
0.0	41.0	3.3	1.08
1.5	32.2	2.4	1.01
3.0	25.7	1.8	1.00
6.0	18.4	1.2	1.00
9.0	14.6	0.8	1.00
13.5	11.8	0.5	1.00

5.2 Vertical distribution

Generally, the definition of a mixed-phase cloud is that ice and liquid water particles coexist in a certain cloud volume. For radiative transfer simulations there are different options to realize this mixture, either as a homogeneous mixed single-layer cloud or as a multi-layer cloud with distinct pure ice and liquid water layers. From the in situ measurements presented in Sect. 3.2 it follows that boundary-layer mixed-phase clouds typically consist of two layers with liquid water droplets at cloud top and precipitating ice below. In this sensitivity study we focus on the ability to identify such mixed-phase clouds and how the layering affects the cloud phase retrieval.

Radiative transfer simulations have been performed based on the microphysical measurements on 7 April 2007, presented in Sect. 3. The cloud optical properties were fixed at $\tau=15$, $D_{\text{eff}}=15\ \mu\text{m}$ for liquid water particles and $D_{\text{eff}}=85\ \mu\text{m}$ for ice particles. The cloud was divided into 10 sublayers with a homogeneous liquid water mode of $\tau_W=1.5$ for each layer. One ice layer ($\tau_I=1.5$) was added and shifted from cloud top to cloud bottom. For each simulation the ice indices I_S , I_P and I_A were calculated. The results are given in Table 2.

The results show that all three indices are most sensitive to the upper cloud layer showing the highest values if the ice layer is located at cloud top ($\tau_W^{\text{top}}=0$). Here τ_W^{top} gives the total optical thickness of the liquid water layers located above the single ice layer. The maximum values of $I_S=41$, $I_P=3.3$ and $I_A=1.08$ range above typical values for pure liquid water clouds and below the maximum values of an ice cloud with equal $D_{\text{eff}}=85\ \mu\text{m}$ and $\tau=15$ as used in the simulations of the mixed-phase cloud (cf. Fig. 5, 7 and 11). The spectral slope ice index I_S and the PCA ice index I_P decrease slowly with increasing τ_W^{top} to values of $I_S=12$, $I_P=0.5$ which reaches the range simulated for pure water clouds. Nevertheless, for $\tau_W^{\text{top}} < 10$ and considering the effective diameter of the water particles ($D_{\text{eff}}=15\ \mu\text{m}$) the ice indices I_S and I_P are higher than for pure liquid water clouds. This suggests that these approaches are able to dis-

tinguish typical boundary-layer mixed-phase clouds with a liquid cloud top layer from pure liquid water clouds. It has to be pointed out that the sensitivity of I_S and I_P to mixed-phase clouds will be reduced if a smaller D_{eff} of the ice crystals is assumed. Smaller ice crystals have less absorption which results in reduced differences of I_S and I_P between pure ice and liquid water clouds (cp. Figs. 5 and 7).

The anisotropy ice index I_A deviates from the values of pure liquid water clouds only if the ice layer is at cloud top. This suggests that I_A is suitable only for a discrimination of pure ice and pure liquid water clouds. Typical boundary-layer mixed-phase clouds with liquid cloud top will be identified as pure liquid water clouds. This is consistent with the findings of Chepfer et al. (2002) who found that the particle shape retrieved from two scattering angles at 650 nm wavelength was insensitive to multilayered clouds when τ of the cloud top layer is larger than 2.

6 Case study on 7 April 2007

On 7 April 2007, concurrent radiation and microphysical measurements were conducted along the path of the Cloud-Aerosol Lidar and Infrared Pathfinder Satellite (CALIPSO) over the Greenland Sea as marked in Fig. 1 with B. A stratus cloud field with cloud top up to 1500 m extended from 77.3° N to northwards at the time of the CALIPSO overpass (10:18 UTC). The profile of the total attenuated backscatter signal measured by CALIPSO is shown in Fig. 12a. The lidar could not completely penetrate the optically thick clouds with exception of the cloud edge (<77.4° N). For the investigated cloud the depolarization measurements (not shown here) are not suitable for a cloud phase analysis. Multiple scattering in the optically thick clouds increased the depolarization regardless of particle shape. Nevertheless, the lidar profiles reveal that in the southern part of the cloud deck (see Fig. 1 and left-side of Fig. 12a) ice particles are precipitating down to the surface. These precipitation particles, which are also observed from CloudSat (reflectivity), can be detected by the Lidar because they are not capped by a liquid water layer in this area.

This part of the cloud was sampled with in situ microphysical instruments about 1 hour before the CALIPSO overpass. Considering the advection of the cloud field with the northerly winds the measurements showed that the cloud edge in the southern part consisted of ice particles only (Fig. 12b, <77.4° N). The particle concentration measured by the CPI increases up to $N_{\text{tot}}=3\ \text{cm}^{-3}$. First liquid water particles were observed with the FSSP 3 km further north. After the descent below the cloud base (77.5° N to 77.6° N) the partly high ice crystal concentrations with simultaneous absence of liquid water particles is related again to precipitating ice below the cloud. Higher cloud layers are probably of mixed-phase as measured during the ascent through the cloud (77.6° N to 77.7° N).

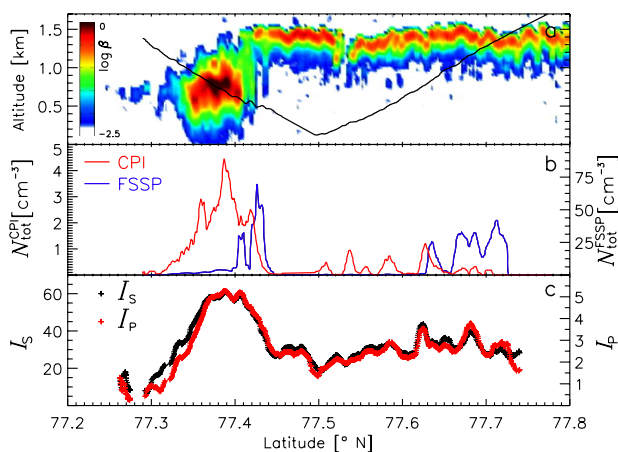


Fig. 12. Profile of total attenuated backscatter coefficient β [$\text{sr}^{-1}\text{km}^{-1}$] measured by CALIPSO in the cloud observed on 7 April 2007 (a). The flight track of the in situ measurements is overlaid as a black line. Ice and liquid water particle concentrations N_{tot} measured by CPI and FSSP along the flight track and the ice indices I_S and I_P for the same positions are given in panel b and c.

Shortly after the CALIPSO overpass the cloud was investigated again by radiation measurements flying above the cloud top. From the measured cloud top reflectance the cloud phase was remotely identified using the ice indices defined above. Figure 12c shows the measured spectral slope ice index I_S and PCA ice index I_P along the flight track of 7 April 2007. Both ice indices show high values around 77.4°N which correlates with the high ice particle concentration measured by the in situ instrumentation one hour earlier. The maximum values of $I_S=60$ and $I_P=5$ indicate a pure ice cloud when compared to the simulations shown in Fig. 5. With measured values of $D_{\text{eff}}=85\ \mu\text{m}$ and $\tau=15$, the simulations for $D_{\text{eff}}=90\ \mu\text{m}$ and $\tau=15$ show values of I_S and I_P similar to the ice indices calculated from the measurements.

Lower values ($I_S=20\text{--}40$ and $I_P=2\text{--}4$) corresponding to mixed-phase clouds assuming unchanged D_{eff} and τ were measured later when the FSSP measured significant liquid water particle concentrations. With respect to the sensitivity studies of Sect. 5, I_S and I_P measured above the mixed-phase clouds are higher than expected and close to values of pure ice clouds with small effective diameter. This reveals that either the fraction of ice crystals is much higher than measured by the in situ measurements or the vertical distribution of the ice differs from the assumption of a liquid cloud top layer with high ice concentrations below.

The analysis of the reflectance-albedo ratio β_I also reveals the presence of ice at the cloud edge. Figure 13 shows all measurements taken on 7 April 2007, above clouds ($\theta=71^\circ$). Generally the measured values of β_I deviate from the theoretical curve of pure liquid water clouds (1-D simulations) which is not expected for mixed-phase clouds with a thick liquid layer at cloud top (cp. Sect. 5.2). The high values of β_I

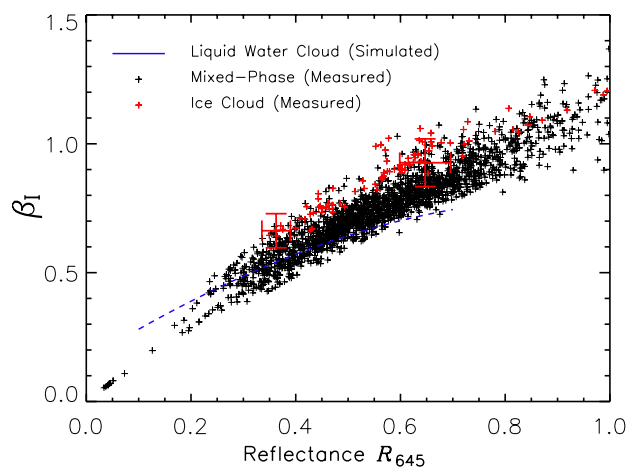


Fig. 13. Measured β_I as function of R_{645} . Black crosses show measurements over mixed-phase clouds, red crosses over the ice cloud observed on the cloud edge. Simulations for pure liquid water clouds are shown as a blue line.

indicate the presence of ice crystals at the top of the mixed-phase clouds. It has to be pointed out here that due to the combination of three separate measurements (F_λ^\downarrow , F_λ^\uparrow and I_λ^\uparrow) the uncertainties of the data points are relatively high as marked at two measurements samples in Fig. 13. Furthermore, the 1-D simulations used to define the anisotropy ice index I_A do not account for possible 3-D radiative effects. Nevertheless the measurements above the cloud edge (labeled by red crosses) tend to range in higher values of β_I . This shows that at the cloud edge nonspherical ice crystals were present at cloud top.

7 Conclusions

Three different methods to derive the cloud thermodynamic phase from airborne spectral solar radiation measurements are presented. The ice index I_S analyzing the slope of the spectral reflectance and the ice index I_P obtained from PCA are capable to identify the cloud phase of Arctic boundary-layer clouds observed during ASTAR 2007. In a case study a pure ice cloud at the edge of a mixed-phase cloud field also probed by in situ microphysical probes and observed by CALIPSO shows significantly higher values of I_S and I_P related to ice particles. The mixed-phase clouds inside the cloud field have lower ice indices than the ice cloud but higher values than expected for pure liquid water clouds.

A third ice index I_A based on the anisotropy of the reflected radiation and defined by the ratio between cloud reflectance and albedo is not able to detect mixed-phase clouds. Simulations show that I_A is mainly affected by the uppermost cloud layers. The optical thickness of the relevant cloud layer was found to be less than $\tau < 1.5$. Therefore, mixed-phase

clouds with liquid cloud top will be identified as pure liquid clouds. Nevertheless, for the edge of the cloud field the presence of nonspherical ice crystals is confirmed.

At least for the cloud top layer the anisotropy ice index I_A is theoretically a more robust indicator for the cloud phase than the spectral slope ice index I_S and the PCA ice index I_P . Sensitivity studies have shown that both indices I_S and I_P are strongly dependent on the ice particle effective diameter and less dependent on cloud optical thickness for $\tau < 5$. Nevertheless, an ambiguity in the discrimination of ice and liquid water phase occurs only between pure ice clouds with small ice crystals and low τ and pure liquid water clouds of high τ . More crucial is the dependence on the ice particle effective diameter for the discrimination between mixed-phase and pure ice clouds. Here, a priori knowledge about the ice crystal dimensions is required.

The case study has shown, that the anisotropy ice index I_A is more difficult to interpret than I_S and I_P . The combination of three independent measurements and possible 3-D radiative effects result in a higher uncertainty of this method. From a single measuring point the retrieval of the cloud phase is not reliable. Cluster analysis or averaging is necessary.

Considering the advantages and uncertainties of all three methods, we suggest to rely on a combination of the methods in further studies. Together with airborne lidar and in situ microphysical measurements such as presented here, further investigations will help to verify algorithms for cloud phase identification from satellites (CALIPSO, CloudSat, MODIS). Especially airborne hyperspectral camera systems resolving the near infrared wavelength range will be capable of investigating the detailed horizontal distribution of ice and liquid water particles.

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