

Retrospect on the tsunami simulation efforts for the German-Indonesian Tsunami Early Warning System

Natalja Rakowsky, Alexey Androsov, Annika Fuchs, Sven Harig, Antonia Immerz, Jörn Behrens*, Wolfgang Hiller, Sergey Danilov, Jens Schröter

Alfred Wegener Institute, Bremerhaven

* KlimaCampus, University of Hamburg, Germany

EGU General Assembly 2014
29 April - 2 May 2014
Vienna, Austria



Outline

- GITEWS overview
- Evolution of TsunAWI and the scenario repository
- Focus: dataproducts
- Focus: scenario selection
- Focus: inundation sensitivity study

GITEWS Timeline

German-Indonesian Tsunami Early Warning System



2005-2011 GITEWS project funded by BMBF

Nov. 2008 Inauguration of the tsunami early warning system in Jakarta

Sep. 2010 Evaluation by international experts

March 2011 Transfer of Ownership to Indonesia

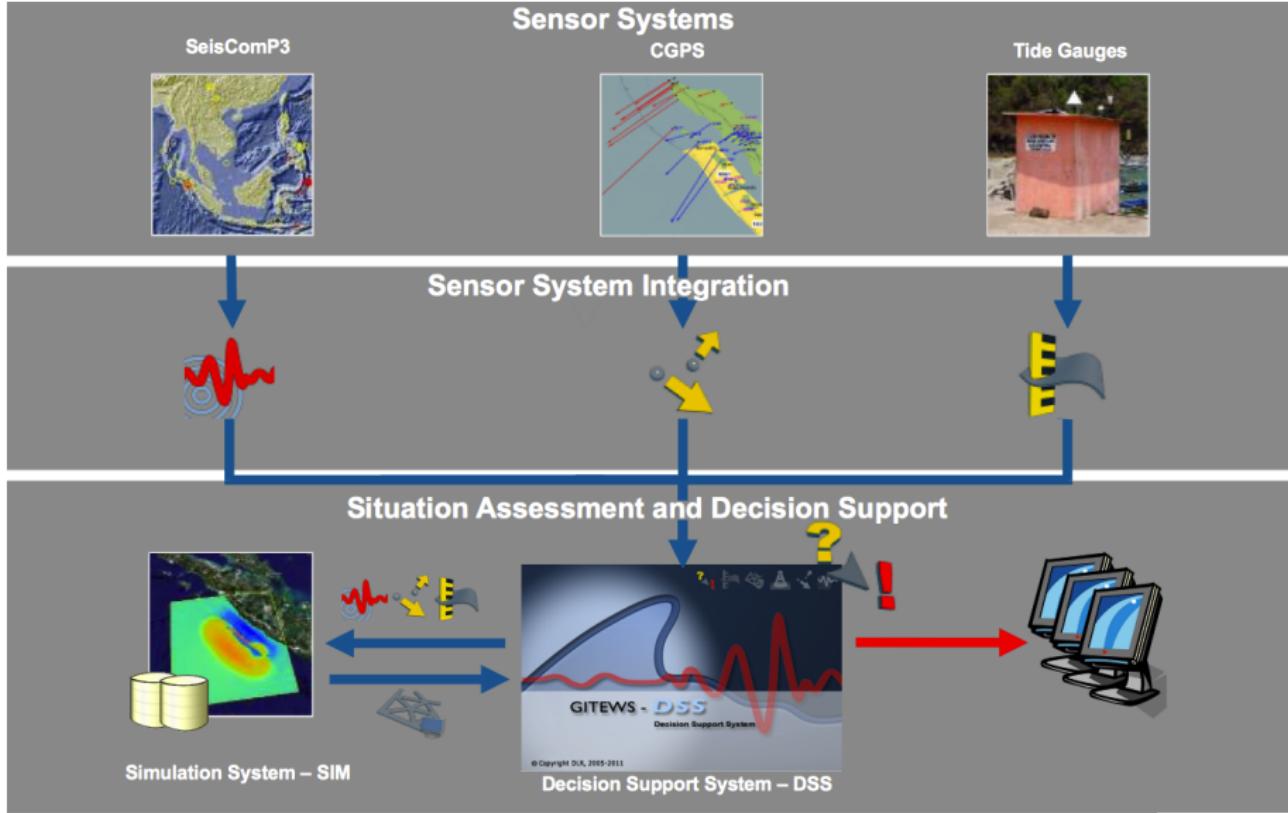
2011-2014 PROTECTS – PROject for Training, Education and Consulting for Tsunami early warning Systems, BMBF



UNITED NATIONS
UNIVERSITY

...

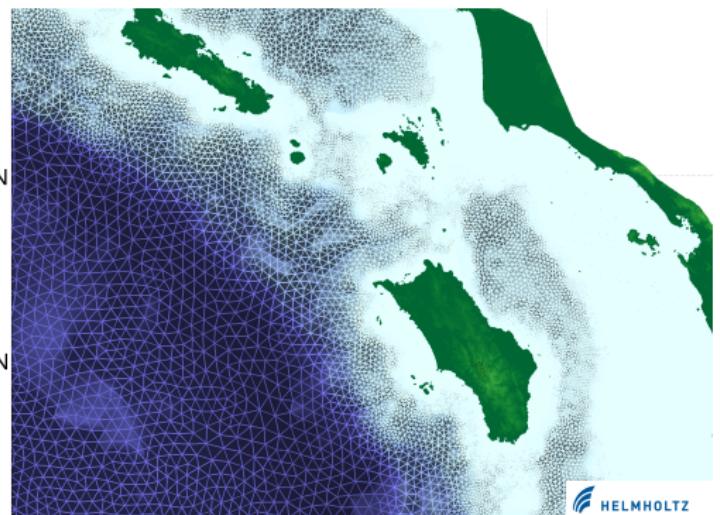
GITEWS System Overview



TsunAWI

In a nutshell

- Non-linear SWE (sibling of full ocean model FESOM),
- Unstructured $P_1 - P_1^{\text{NC}}$ finite element grid, $\Delta x \leq \min \left(c_t \sqrt{gh}, c_g \frac{h}{\nabla h} \right)$
- Initial conditions: Okada parameters, source model, land slide model
- Leap-frog time stepping
- Modules for tides,
non-hydrostatic pressure
- Fortran90, OpenMP, netcdf
- Visualization with Matlab,
OpenDX, GIS
- Scripts for batch and post
processing, shapefile output



TsunAWI scenario repository

Scenarios 2007-2010

model physics linear shallow water

source model by GFZ: RuptGen 1.0, 1900 sources

336 epicenters, Mw=7.5, 7.7, **8.0**, 8.2, **8.5**, 8.7, **9.0**

bathymetry GEBCO 1', accurate datasets for coastal regions

TsunAWI scenario repository

Scenarios 2007-2010 → since 2011

model physics linear shallow water

- nonlin. advection added, Smagorinsky viscosity, improved inundation scheme

source model by GFZ: RuptGen 1.0, 1900 sources

336 epicenters, Mw=7.5, 7.7, **8.0**, 8.2, **8.5**, 8.7, **9.0**

- RuptGen 2.1, 3470 sources
528 epicenters, Mw=7.2, 7.4, 7.6, ..., 8.8, 9.0

bathymetry GEBCO 1', accurate datasets for coastal regions

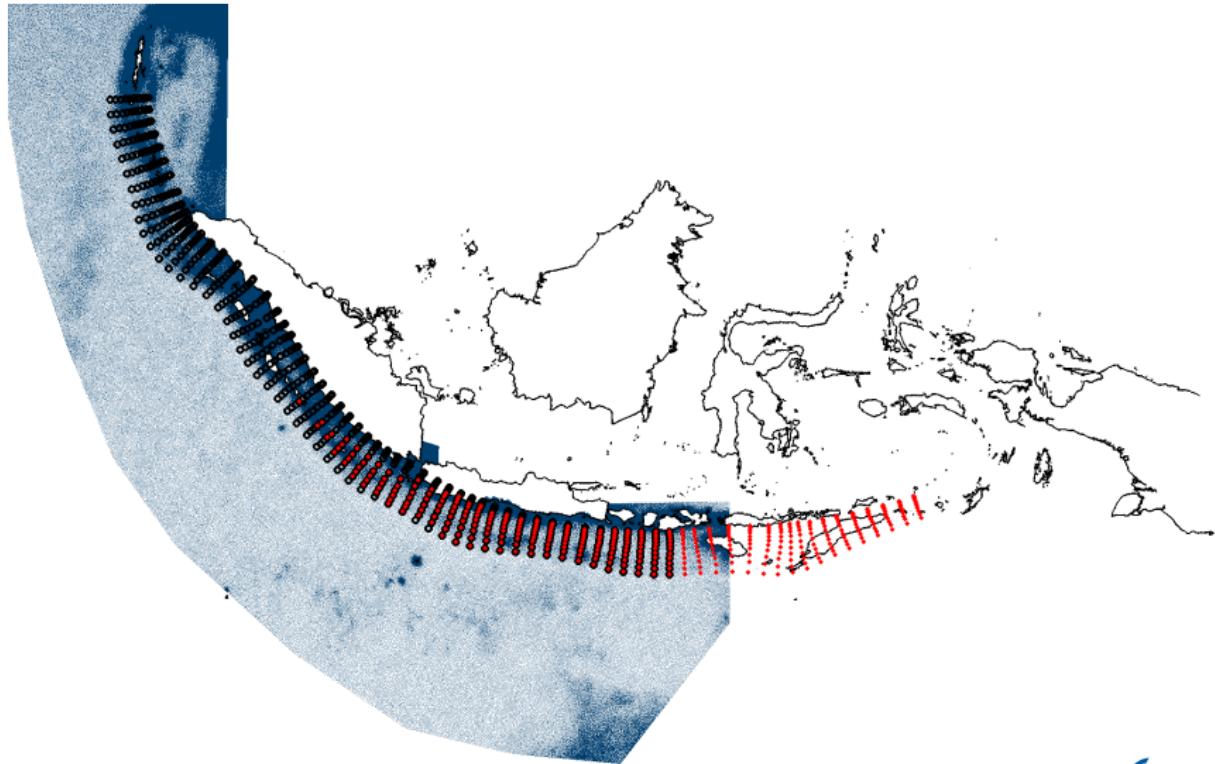
- GEBCO 30" instead of GEBCO 1'

technical improvements

- faster calculation, reduced scenario file size

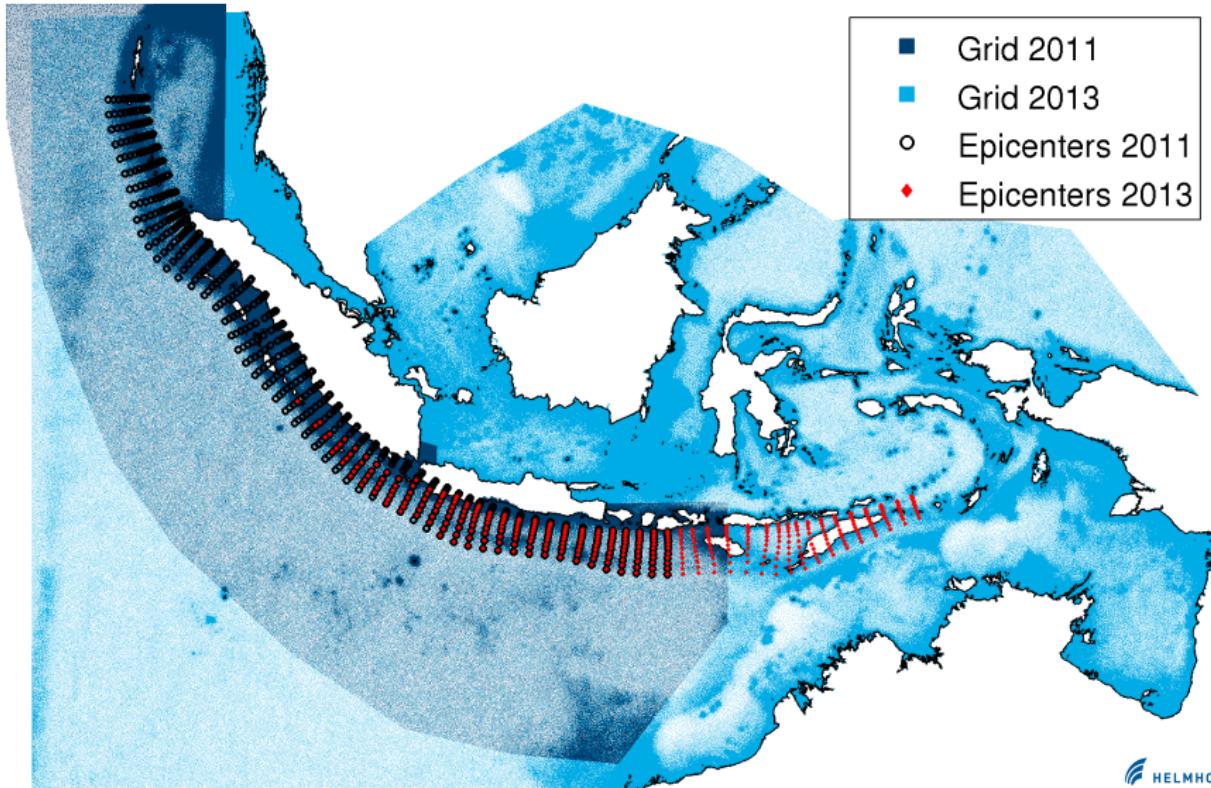
TsunAWI scenario repository

Model domain for scenarios 2011



TsunAWI scenario repository

Model domain for scenarios 2011 and extension 2013



TsunAWI scenario repository

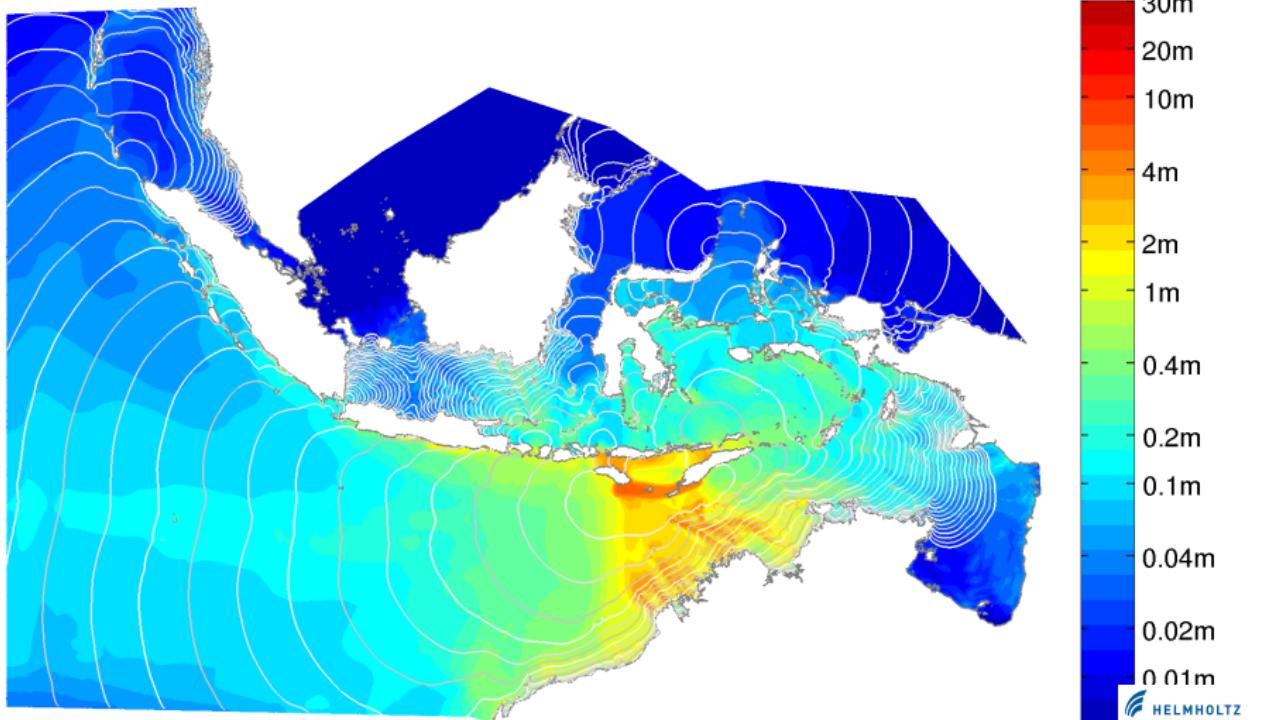


	Scenarios 2011	Extension 2013
#scenarios	3450	New, East: 1100 Replace: 1100
magnitudes	7.2, 7.4, ..., 8.8, 9.0	
#grid nodes reduced	2.3 Mio 1.1 Mio	15 Mio 7.5 Mio
resolution	50m - 150m - 15km	
model time	3 h	12 h
compute time	0:45 h 2× 8 Core Xeon Nehalem	15 h 1× 8 Core Xeon Westmere
file size	1.1GB	22GB → 500MB without timesteps

Scenario data products

ETA isochrones and maximum amplitude

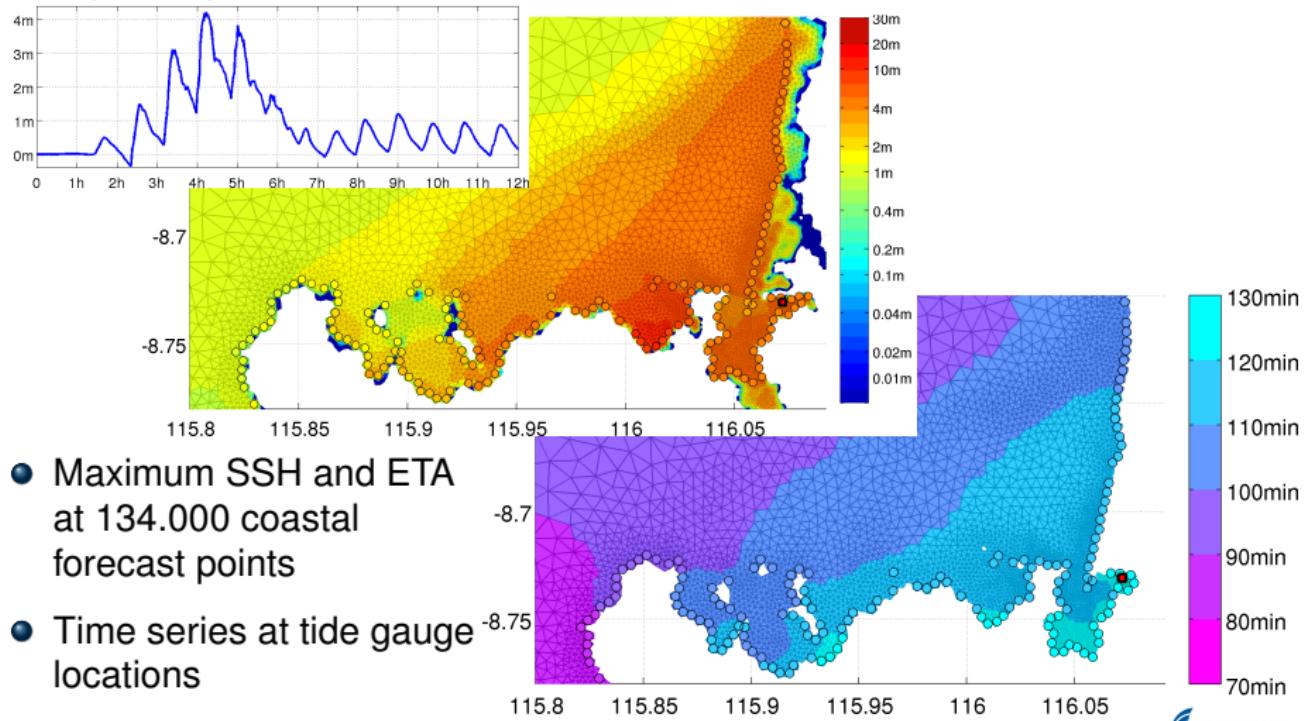
Example: Magnitude 9.0 in the Eastern Sunda Arc



Scenario data products

Coastal forecast points

Example: Magnitude 9.0 in the Eastern Sunda Arc, zoom to Lembar, Eastern Lombok



- Maximum SSH and ETA at 134.000 coastal forecast points
- Time series at tide gauge locations

Scenario selection algorithm

Uncertainty reduction with multiple sensors

Regard each sensor type with its characteristics in mind!

- Epicenter and magnitude are derived from multiple sensor data by approved SeisComP3.
- Reliable GPS data comes fast, too. But little experience so far, limited number of stations.
- Tide gauges hard to use for **early** warning in a fully **automated** algorithm.

Scenario selection algorithm

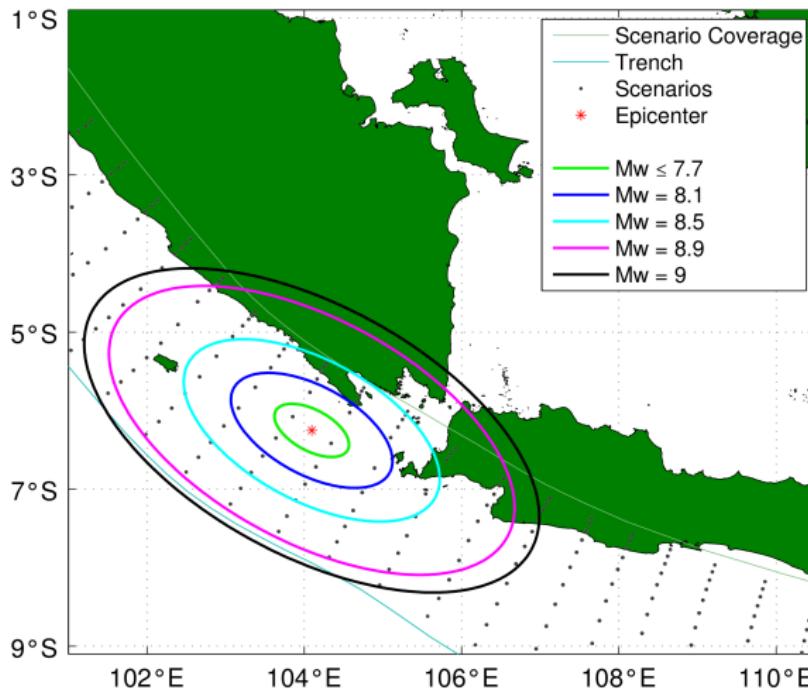
Uncertainty reduction with multiple sensors

Regard each sensor type with its characteristics in mind!

- Epicenter and magnitude are derived from multiple sensor data by approved SeisComP3.
→ Use epicenter and magnitude to pre-select scenarios.
- Reliable GPS data comes fast, too. But little experience so far, limited number of stations.
→ Refine scenario selection by comparing GPS measurement and scenario data.
- Tide gauges hard to use for early warning in a fully automated algorithm.
→ Very valuable for all-clear and hind-casts.

Scenario selection algorithm

1. Step: Seismic pre-selection



Magnitude uncertainty:
 $[M - 0.5; M + 0.3]$,

$M_w + 0.2$ for momentum tensor Magnitude

Epicenter uncertainty:

Ellipse parallel to the trench

$$r_L = 10^{0.5[M+0.3]-1.8} \text{ km},$$

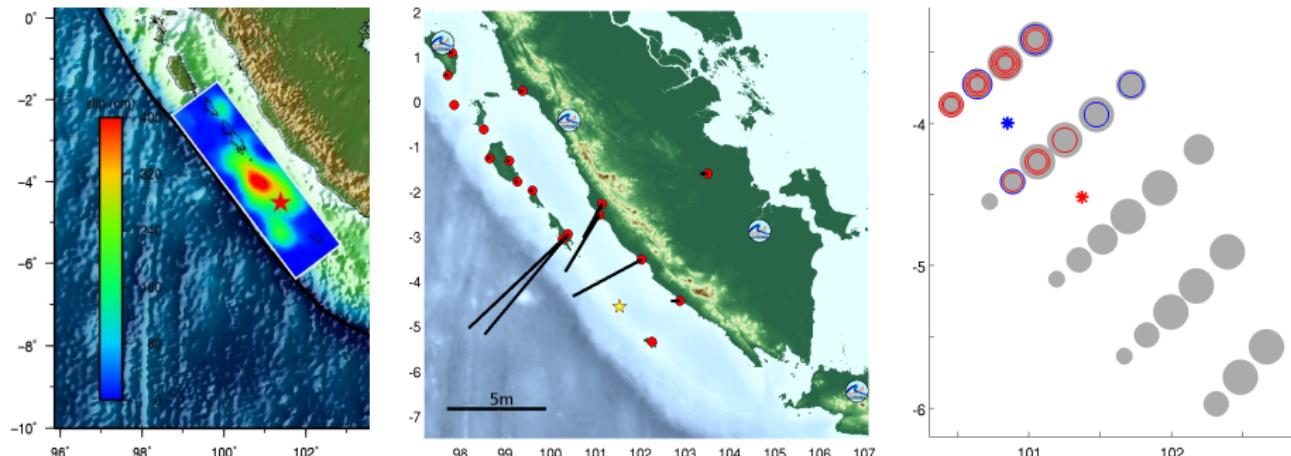
$$r_W = \frac{1}{2} r_L.$$

Scenario selection algorithm

2. Step: Refine selection with GPS data

e.g., Benkulen Sept. 2007

USGS Finite Fault: Tsunami source NW of the epicenter.
Measured GPS-dislocations strong in the NW, but not SE.



GPS matching would reject all scenarios in the SE, and some very strong scenarios in the NW.

Inundation simulation

Sensitivity study on topography data

Three groups AIFDR, ITB, AWI,

Three models ANUGA, TUNAMI-N3, TsunAWI,

Three regions Padang (Sumatra), Maumere (Flores), Palu (Sulawesi)

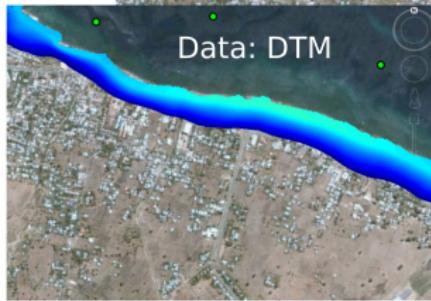
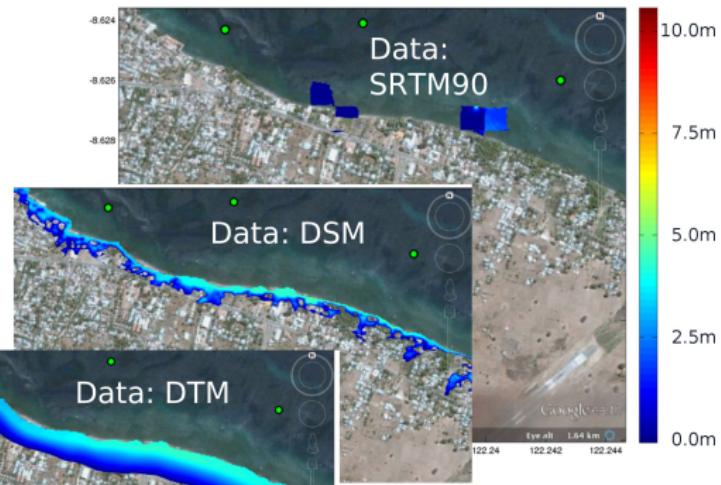
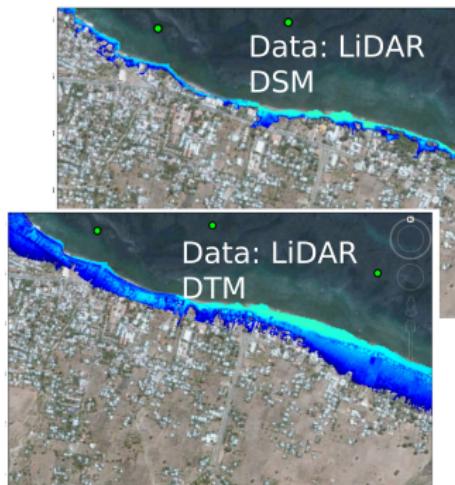
One conclusion **High quality topography data is crucial!**

- Free SRTM data (90m horizontal resolution, $\leq 16\text{m}$ vertical accuracy) only for rough estimates,
- Intermap (5m; 0.7m) and LiDar (1m; 0.15m) comparable for shallow water models,
- Results more sensitive to varying data sets than to varying resolution.

Inundation simulation

Sensitivity study on topography data

Example: synthetic scenario for Maumere, Flores



Resolution: 2m

Outline

- GITEWS overview
- Evolution of TsunAWI and the scenario repository
- Focus: dataproducts
- Focus: scenario selection
- Focus: inundation sensitivity study

Thank You, Terima Kasih!

Poster: B238